



GEYA

GEYA ELECTRICAL CO.,LTD

ELECTRICAL

浙江格亚电气有限公司

地址：浙江省乐清市北白象温州大桥工业区 325603
电话:0577-62771036
传真:0577-62711079
手机:13567770207
E-mail:sale@cnyeya.com
Web:www.cnyeya.com

GEYA ELECTRICAL CO.,LTD

Add:Wenzhou Brige Industrial Zone,Beibaixiang Town,
Yueqing,Zhejiang,China 325603
Tel:0086-577-62771036
Fax:0086-577-62711079
Mobile:0086-13567770207
E-mail:sale@cnyeya.com
Web:www.geya.net

GEYA
www.geya.net



2018

Air Circuit breaker
Product catalog





GEYA
www.geya.net

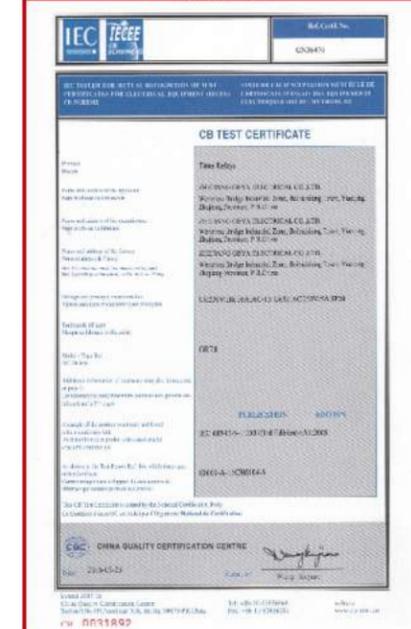
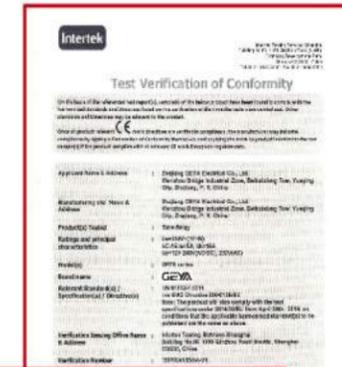
Everything for your electricity safety!

一切,为了您的用电安全!
★★★★★



Introduction

Geya Electrical was established in 2005, and our head office is based in Wenzhou China. Our products are exported to more than 20 countries and regions such as South America, Western Europe, the Middle East, Africa, Australia, South Asia, East Asia, etc. Geya is ISO9001 Quality Assurance accredited and both quality and safety are of paramount importance to us. Our products have SEMKO VDE and CE certificates. Our experience and expertise in modern, innovative product design, vast OEM experience, constant new product development, strong R&D capabilities, competitive prices, excellent international market knowledge, professional dynamic and customer-focused staff, flexible trading terms, quality and timely deliveries.



CONTENTS

| | |
|---|-------|
| I. Usage and scope of application | 1 |
| II. Model meanings and classifications | 1 |
| III. Normal working and installation conditions | 2 |
| IV. Introduction of structure | 3 |
| V. Technical data and performance | 4 |
| VI. Structure overview | 13 |
| VII. Internal Wiring Mode | 15-20 |
| VIII. Installation and overall dimensions | 21-26 |
| IX. Dimensions and mounting holes spacing of door frame | 26 |
| X. Installation, operation and maintenance | 27-31 |
| XI. Common faults and solving measures | 32 |
| XII. Specifications of ordering | 33 |

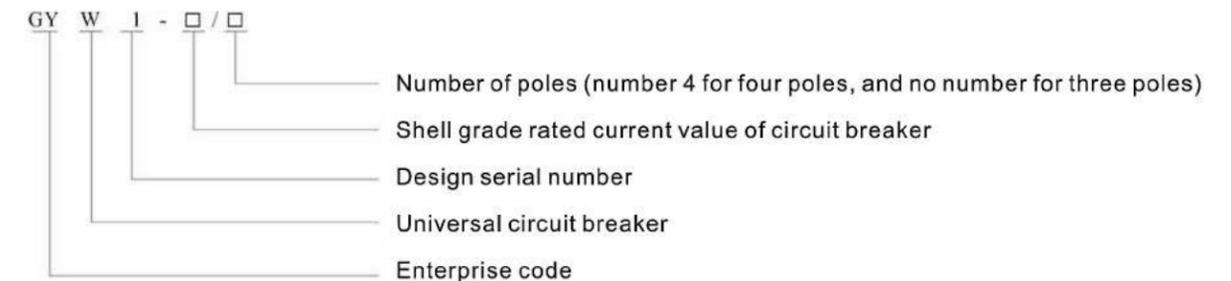


1 Usage and scope of application

GYW1 series intelligent circuit breakers (hereinafter referred to as circuit breakers), are suitable for distribution networks of AC 50Hz, rated voltage up to 660V (690V) and rated current of 630A~6300A, and are used to distribute electric energy and protect the circuit and power supply equipment from overload, under-voltage, short circuit, single-phase grounding and other failures. The circuit breaker has the intelligent protection function, of which the selective protection is accurate, enhancing the power supply reliability and avoiding the unnecessary power failure. Meanwhile, it is equipped with open communication interfaces, which enable the "four remote" functions, meeting the requirements of the control center and automation system. The impulse withstand voltage of the circuit breaker at an altitude of 2,000 meters is 8,000V (the voltage varies with different altitudes according to relevant standards, and the maximum value is 12,000V). When it is not equipped with any intelligent controller and sensor, the circuit breaker can be used as an isolator, with the mark "I". The circuit breaker complies with the requirements of the standards GB14048.2 "Low voltage switchgear and controlgear- Part 2: Low voltage circuit-breakers" and IEC60947-2 "Low-voltage switchgear and controlgear- Part 2: Circuit-breakers", etc.

2 Model meanings and classifications

○ Model and meaning



○ Type

Classified by mounting methods

1. Fixed type
2. Withdrawable type

Classified by the numbers of poles: Three-pole, four-pole

Classified by operation modes:

1. Power operating,
2. Manually operated (for maintenance and repair)

○ Type of release

Intelligent controller, under-voltage instantaneous (or time-delay) release, shunt release.

○ Properties of intelligent controller:

1. Intelligent controllers are divided into: H-type (for communication), M-type (standard model), L-type (economical model);
2. It has various functions, such as overload long-delay inverse time-lag, short-delay inverse time-lag, constant time-lag and instantaneous time-lag. Users can themselves set the protection features according to practical needs;
3. Single phase grounding protection function;
4. Display function: Display of setting current, action current and voltages in each phase (voltage display function should be indicated when ordering);
5. Alarm function: Overload alarm;
6. Self-inspection function: Overheat self-inspection and microcomputer self diagnosis;
7. Test function: Test the operating characteristics of the controller.

3 Normal working and installation conditions

○ Ambient air temperature

The ambient working temperatures shall not be higher than +40°C or lower than -5°C, and the average value of 24h shall not be higher than 35°C.

Note: If users' ambient working temperature exceed required values, they should discuss it with our company.

○ Atmospheric conditions

The atmospheric relative humidity should not be higher than 50% when the ambient working temperature is +40°C, and should be comparatively higher in case of low working temperature; the maximum average relative humidity in the wettest month is 90%, and meanwhile the minimum average temperature of this month is +25°C, considering the condensation on product surface due to temperature changes. If users' working conditions cannot meet the above-mentioned requirements, please discuss with our company.

○ Protection grade: IP30

○ Class of pollution: III

○ Category of operation: Category B

○ Type of installation

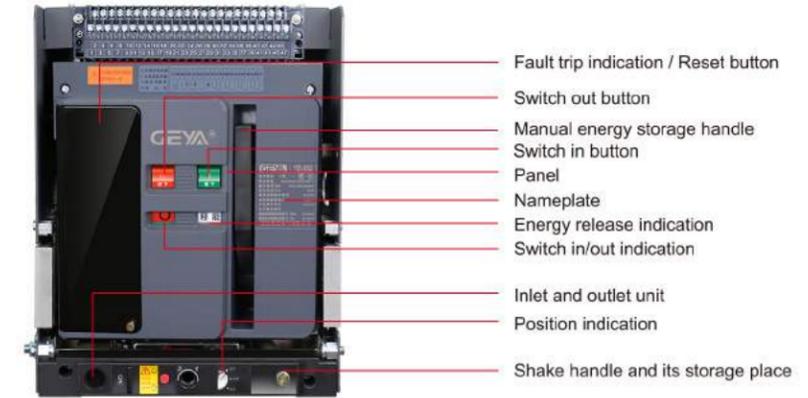
Circuit breakers with rated operating voltages of 660V (690V) or below and under-voltage release, the primary coil of power transformer adopts Type IV, and the installation type of auxiliary circuit and control circuit is Type III.

○ Installation conditions

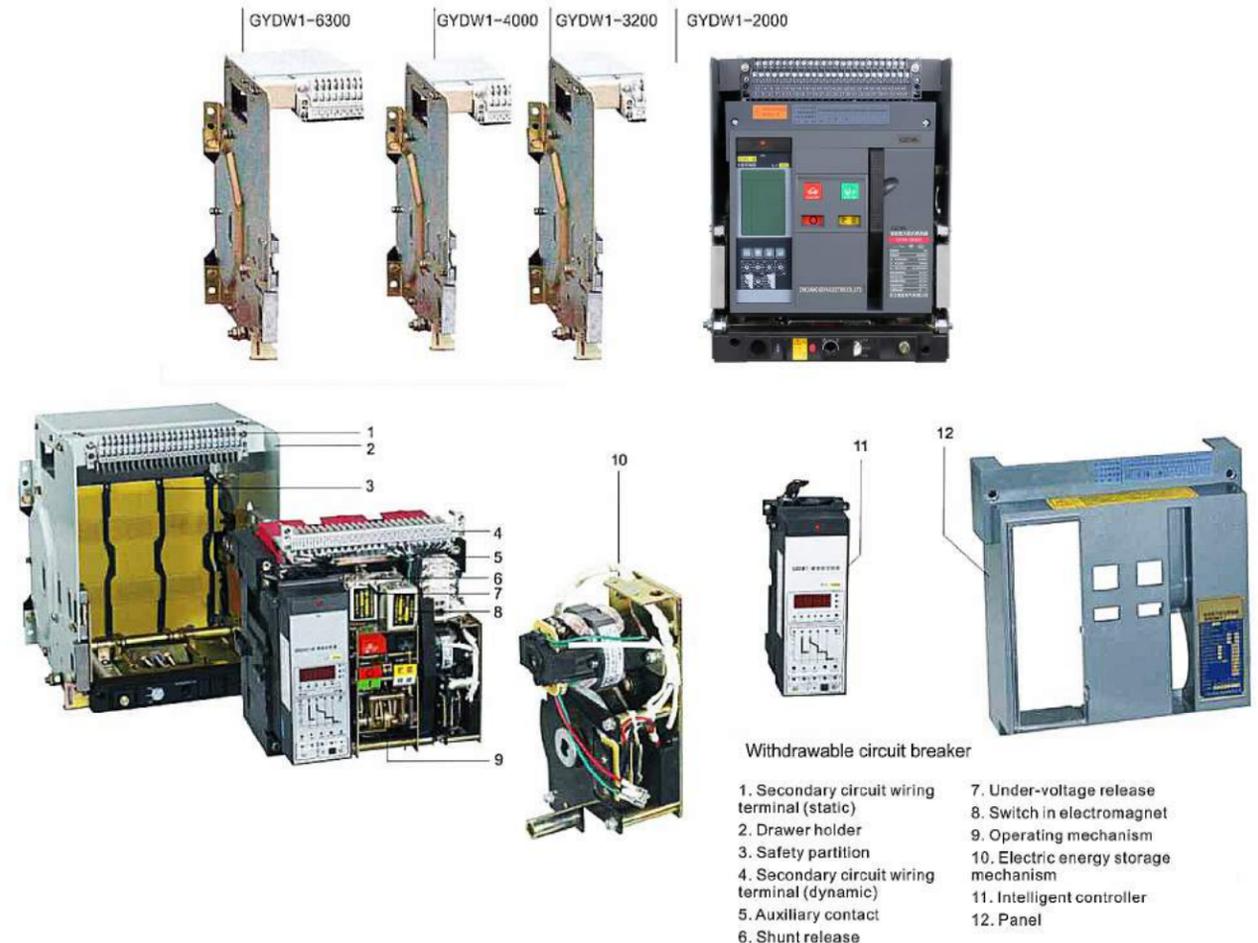
The circuit breaker should be installed as required by this Manual, with the vertical inclination of circuit breaker not more than 5° (the inclination of mine-used circuit breaker should not exceed 15°).

4 Introduction of structure

○ Front indication of circuit breaker



○ GYDW1 series Intelligent Universal Circuit Breakers



5 Technical data and performance

Rated current of circuit breaker

Table 1

| Shell grade rated current in mA | Rated current in A |
|---------------------------------|----------------------------------|
| 2000 | 630, 800, 1000, 1250, 1600, 2000 |
| 3200 | 2000, 2500, 2900, 3200 |
| 4000 | 3200, 3600, 4000 |
| 6300 | 4000, 5000, 6300 |

The rated short-circuit breaking capacity and short-time withstand current of the circuit breaker, and the arcover distance of circuit breaker is "0" (i.e. there is no arcover outside the circuit breaker)

Table 2

| Shell grade rated current in mA | 2000 | 3200 | 4000 | 6300 |
|--|------|------|------|------|
| Rated ultimate short-circuit breaking capacity Icu (kA) O-CO | 400V | 65 | 100 | 138 |
| | 690V | 50 | 65 | 105 |

| | | | | | |
|--|------|----|----|----|-----|
| Rated operating short-circuit analysis capacity Ics (kA) O-CO-CO | 400V | 50 | 65 | 65 | 138 |
| | 690V | 40 | 50 | 50 | 105 |
| Rated short-time withstand current Icw (kA) 1s, delay 0.4s, O-CO | 400V | 50 | 65 | 65 | 138 |
| | 690V | 40 | 50 | 50 | 105 |

Note: The breaking capacity in the table has the same upper and lower incoming lines

The maximum power consumption of circuit breaker is 360W. The changes of the rated continuous current of circuit breaker at different ambient temperatures are as shown in Table 3

Table 3

| Inm | GYDW1-2000 (Frame I) | | | | | | GYDW1-3200 (Frame II) | | | | GYDW1-6300 (Frame III) | | | | |
|---------------------|----------------------|------|------|-------|-------|-------|-----------------------|-------|-------|-------|------------------------|--------|--------|-------|-------|
| | In | 630 | 800 | 1000 | 1250 | 1600 | 2000 | 2000 | 2500 | 2900 | 3200 | 4000/3 | 4000/4 | 5000 | 6300 |
| Ambient temperature | 40 | 630A | 800A | 1000A | 1250A | 1600A | 2000A | 2000A | 2500A | 2900A | 3200A | 4000A | 4000A | 5000A | 6300A |
| | 50 | 630A | 800A | 1000A | 1250A | 1550A | 1900A | 2000A | 2400A | 2900A | 2900A | 3800A | 3800A | 4500A | 6000A |
| | 60 | 630A | 800A | 1000A | 1250A | 1550A | 1750A | 2000A | 2250A | 2900A | 2850A | 3600A | 3600A | 4200A | 5400A |

Protection features and functions of intelligent over-current controller

Protection features of over-current controller

1. The setting value Ir(I/In) and tolerance of the controller is as shown in Table 4

Table 4

| InmA | Long delay Ir1 | Short delay Ir2 | | | Instantaneous Ir3 | | | Grounding fault Ir4 | |
|-------|----------------|-----------------|--------------------------------|-----------|-------------------|---------------|-----------|--|-----------|
| | | L-type | M and H types | Tolerance | L-type | M and H types | Tolerance | Inm=2000~4000A (0.2~0.8)In Max. 1200A Min. 160A | Tolerance |
| 2000 | (0.4-1)In | (3-10)In | M:(0.4-15)Ir1 H:(1.5-15)Ir1 | ±10% | (3-10)In | In~50kA | ±15% | Inm=6300A (0.2~1)In | ±10% |
| ≥3200 | | | | | (7-14)In | | | | |

Note: When there are three sections of protection at the same time, the setting values cannot be intersected, and should follow the sequence Ir1<Ir2<Ir3.

2. Long delay over-current protection reverse time-lag actuation characteristics where the actuation time of (1.05~2.0)Ir1 is as shown in Table 5, with a time tolerance of ±15%.

Note: tL- the setting time of long delay 1.5Irs, TL- the actuation time of long delay.

Table 5

| 1.05Ir1 | 1.3Ir1 | 1.5Ir1 setting time S | 15 | 30 | 60 | 120 | 240 | 480 |
|------------------|-------------|-------------------------|-----|------|------|------|-----|-----|
| >2h no actuation | <1h actuate | 2.0Ir1 actuation time S | 8.4 | 16.9 | 33.7 | 67.5 | 135 | 270 |

3. Short delay over-current protection characteristics are as shown in Table 6

Table 6

| Delay setting time ts (s) | 0.1 | 0.2 | 0.3 | 0.4 |
|---------------------------|------------------------------------|-------------------------------|------|-------------------|
| Delayable time (s) | 0.06 | 0.14 | 0.23 | 0.35 |
| Actuation characteristics | I>8Ir1 constant time-lag actuation | | | |
| | I < 8Ir1 | $T = \frac{(8Ir1)^2 ts}{I^2}$ | | T= actuation time |

Properties of M-type intelligent controller:

1. Ammeter function

It displays the running currents in each phase and the grounding leakage current; it normally displays the current in the maximum phase, and also displays the setting, testing and fault current values or time values.

2. Voltmeter function

It displays the voltages in each line and normally displays the maximum value.

3. Remote monitoring and self-diagnostic function

1) The controller has a self-diagnosis function on faults

When the computer fails, it can display a digit "E" representing running error or give an alarm, and reboot the computer at the same time; and if needed by users, it can also switch out the circuit breaker.

2) When the local ambient temperature reaches 80℃, it sends out an alarm, and can switch out the circuit breaker at a smaller current (if required by users).

3) The intelligent controllers can output overload, short circuit, grounding, load monitoring, pre-alarm and release indication (OCR) signals through contacts or optocouplers, making it convenient for users to connect external remote control; the capacity of the contact is DC28V, 3A and AC125V, 3A.

4. Setting function

Various parameters of the controller can be tuned by pressing the four buttons. 设定 存储 Press the 设定 button to reach desired state (state indicator light), then press the 存储 button to tune the parameters into desired values; then press the 存储 button again to and the storage indicator light blinks one time, indicating the setting value having been locked. The protection parameters of the controller should not be set intersecting with each other. After resetting the controller by reconnecting the power supply, press the 设定 button can circularly check various parameters that have been set.

5. Test function

Pressing the 设定 测试 脱扣 不脱扣 复位 buttons can set up a test current for fault analog (note: do not lock it by pressing the 存储 button), then press the 测试 or 不脱扣 button to perform the test, and the controller can carry out fault handling. Press the button to switch out the circuit breaker, and press the 测试 button to keep the circuit breaker switched in, while various indication state of the controller keeps normal. After testing, it is necessary to press the 复位 or 请灯 button for once. Then, other tests can be performed.

Note: In order to make the tests convenient, no matter whether the grounding leakage is tuned into release or alarm position, it is regarded as release in the tests, with a priority less than overload protection. In case of faults during tests, the controller automatically stops all tests and goes into faults handling.

6. Load monitoring function

Set two setting values, with a setting range (0.2~1)In for ILC1 and a setting range (0.2~1)In for ILC2, and the delay characteristics of ILC1 is inverse time-lag, and its time setting value is 1/2 of long delay setting value; the delay characteristics of ILC2 are of two types, the first of which is inverse time-lag function and its time setting value is 1/4 of long delay setting value; while the second type is constant time-lag, and its delay time is 60s. Regarding both time delay functions, the former function is used to switch out subordinate unimportant load when the current approaches overload setting value; while when the current exceeds ILC1

setting value, switching out subordinate unimportant load with time delay, the current declines to maintain the power supply in main circuit and important load circuits, and when the current declines to ILC2, the other function sends out the order with certain time delay to re-connect the circuit that having been switched out, so as to resume the power supply for the whole system. Users may select either of the above-mentioned two monitoring protection, and the monitoring characteristics are as shown in Figure 3 and 4.

7. MCR release and analog release protection can be switched off if required by users, and are usually switched off in short delay breaking tests.

1) MCR switching on breaking protection is mainly used when the circuit is in fault switching in state (the moment when the controller is energized), and the controller has the function of switching out the circuit breaker at the low short-circuit current. Factory setting is 10kA, with a tolerance of $\pm 20\%$, and its set-point current can be set according to users' requirements.

2) The controller has the function of directly sending off a release signal without being processed by the host chip in case of an extra-large short-circuit current.

8. Thermal memory function

After the release caused by overload or short circuit and before disconnecting power supply, the controller has the memory function of simulating the characteristics of bimetallic strips; the discharging of overload energy is finished in 30min and the discharging of short delay energy is finished in 15min, and the characteristics of overload and short delay over-current release protection are as shown in Figure1, and the characteristics of grounding fault protection are as shown in Figure 2.

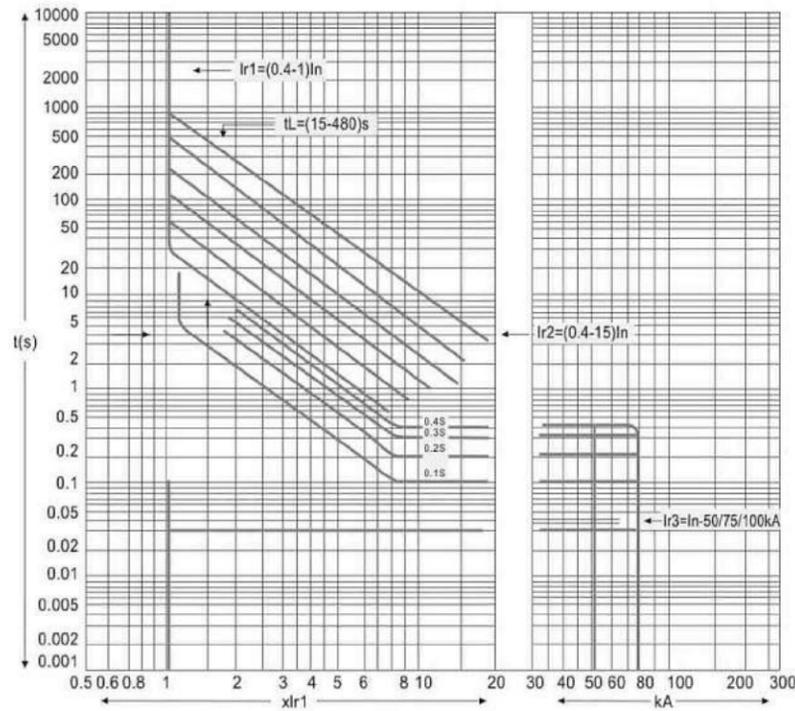


Figure 1

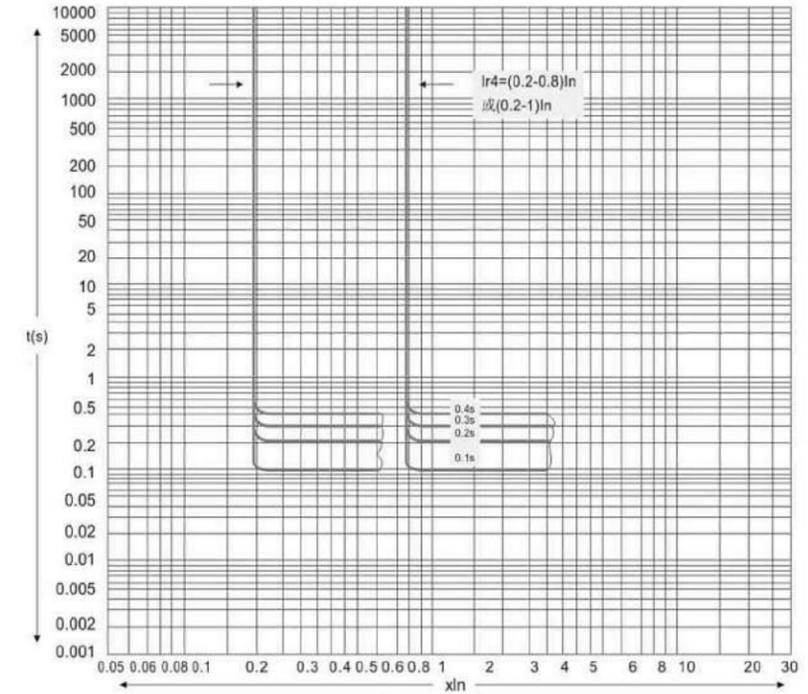


Figure 2

The characteristics of monitoring are as shown in Figure 3 and 4.

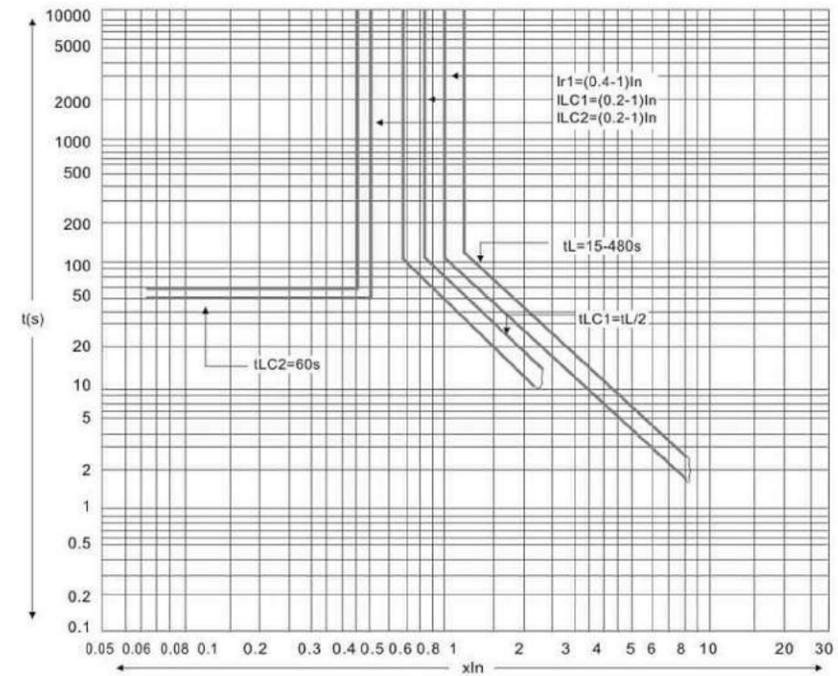


Figure 3

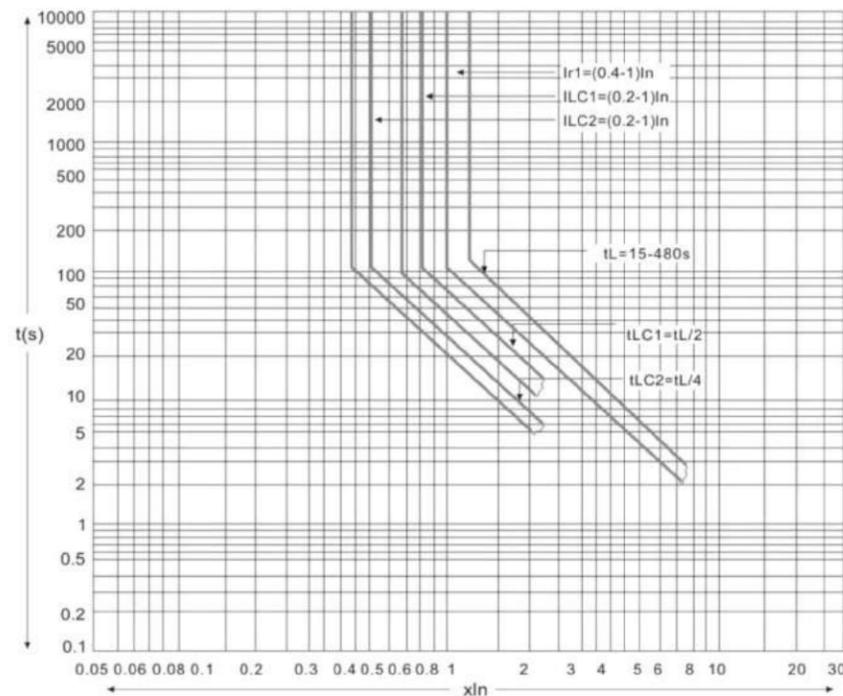
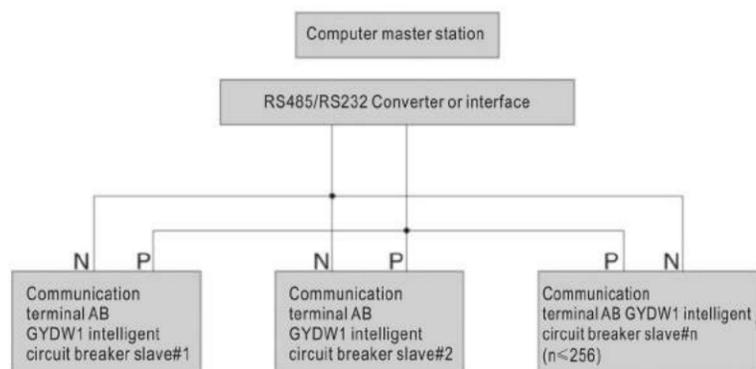


Figure 4

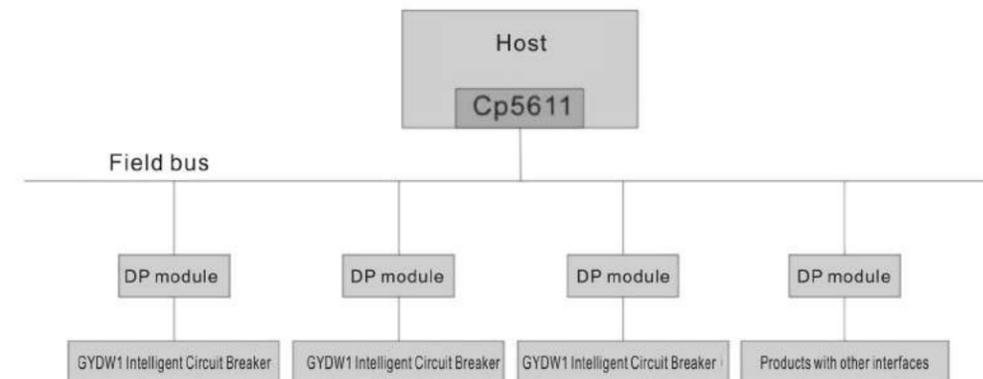
○ H-type intelligent controller

Except for all functions of L-type intelligent controller, L-type intelligent controller is also equipped with serial communication interfaces, through which a LAN system (hereinafter referred to as the System) in the master-slave structure can be constituted, consisting of 1-2 sets of computers as the master station and several intelligent circuit breakers or other communication components as the slave station, and the System network structure is as shown below; regarding the circuit breaker unit, the System can realize the "four remote" control functions: monitoring and measuring of various power grid parameters and operation parameters, monitoring and displaying of the current operation state of intelligent circuit breakers, adjusting and downloading of various protection threshold parameters, and switching in and out of intelligent circuit breakers, etc. The System is suitable for the construction and transformation of power distribution and monitoring systems in various power stations, power plants, power supply, medium-and-small substations, industrial and mining enterprises and buildings, etc.

The connection diagram of proprietary communications protocol interfaces is as follows:



The connection relationship diagram of universal DP protocol based circuit breaker products is as shown in the following figure:



Constitution of the System

Hardware structure of data communication network system

Intelligent circuit breaker provides standard RS485 communication interfaces, which are led out from the NO.10 and 11 outlets of the circuit breaker.

Communication medium for system connection: Shielded twisted pair of Class A.

Network main characteristics

The product adopts a bidirectional serial data transfer mode, making it capable of providing a variety of communication protocols: "Low voltage electrical equipment data transmission protocol V1.0", PROFIBUS-DP and MODBUS, etc.

Strict master-slave mode, i.e. the master station is the initiator and controller of communication and the slave station can only communicate with the master station rather than directly communicating with other slave stations. The communication baud rate is 9600bit/s and the communication distance is 1.2km. For PROFIBUS-DP, typical applications of communication baud rate can reach 187.5kbit/s.

Monitoring software

YSS2000 configuration software can realize the configuration application of required monitoring management software according to different engineering requirements. For intelligent circuit breakers, the operation monitoring and various daily management functions can be realized.

○ System function

Remote control

Remote control refers to controlling the storage, closing and breaking of the first slave station circuit breaker in the system through the master station computer. The operator selects corresponding objects from the system interface by clicking the remote control button with the mouse, and the system provides the current running state of corresponding objects. Operators can give remote controlling "switching in" or "switching out" instructions by inputting the operation passwords. The system transfers the instructions to corresponding circuit breaker slave station, which conducts switching out, switching in, energy storage and

other operations according to given timing sequence after receiving the instructions, and then report remote controlling results to the host station.

Remote adjustment

Remote adjustment refers to setting up the protection constant value of the slave station through the master station computer. The protection constant values tables of all slave stations are stored in the master station computer, operators select corresponding objects by clicking the remote adjustment button on the system interface, then the system displays all current protection constant values of corresponding objects as well as the their protection constant values tables; after inputting operation passwords, operators can select required parameters from the tables, and the host station download selected parameters to corresponding slave stations after operators clicking corresponding buttons, and report remote adjustment results to the host station. After receiving corresponding parameters, the slave station immediately modify its protection constant value.

Remote monitoring

Remote monitoring refers to monitoring the power grid operating parameters of each slave station through the host station in a real-time manner. The working parameters transferred to host computers by the communication substation are as follows: The real-time current values of phases A, B, C and N in each substation, the voltage values of UAB, UBC and UCA.

The fault record can record the following fault parameters.

Current values of phases A, B, C and N, voltage values of UAB, UBC and UCA, type and actuation time of fault, and record the fault in the fault database.

The computer displays the current real-time current values and voltages of each substation in bar diagrams, absolute value tables and other methods, and displays the running state of each node in real-time curve.

Remote communication

Remote communication refers to checking the models, switching in and out states, protection constant values, operating and fault information and other information of the slave stations through the master station computer. Parameters transferred to host computers by the slave station circuit breaker include: Switch type, switching states (in/out), fault information, alarm information and various protection constant values, etc.

Other functions of the system

In addition to the four remote control functions, the system can also carry out a variety of management functions: accident alarm (information screen, screen promotion, event printing, accident dialing, sound alarm), event record, maintenance hanging out, management of shift change, load trend analysis and printing of various types of reports, etc.

L-type intelligent controller

L-type intelligent controllers adopt the encoding switch and toggle switch setting method, which is featured with overload long delay, short-circuit short delay, instantaneous and grounding leakage four-section protection, and has the fault state, load current light indication function and other functions; but it has no digital display, and its functions are not as many as M and H type intelligent controllers. Users can select desired functions in general situations.

Operating performance of the circuit breaker is shown in table 7

table 7

| Inm(A) | Number of operating cycles per hour | Mechanical life (number of times) | | Electrical life (number of times) |
|--------|-------------------------------------|-----------------------------------|-----------------------|-----------------------------------|
| | | Maintenance free | Requiring maintenance | |
| 2000 | 20 | 13500 | 20000 | 6500 |
| 3200 | 20 | 10000 | 20000 | 3000 |
| 4000 | 15 | 5000 | 10000 | 1500 |
| 6300 | 10 | 5000 | 10000 | 1000 |

The shunt release, under-voltage release, electric operating mechanism, energy releasing (switching in) electromagnet of circuit breakers, and the working voltages and required powers of intelligent controllers

table 8

| Items | | Required power | | DC | |
|---|--|-----------------------------|------------|------|------|
| | | Rated working voltage | | 110V | 220V |
| | | 220V(230V) | 380V(400V) | | |
| Shunt release | | 24VA | 36VA | 24W | 24W |
| Under-voltage release | | 24VA | 36VA | - | - |
| Switching in electromagnet | | 24VA | 36VA | 24W | 24W |
| Power operating mechanism | Shell grade rated current of circuit breaker | 2000A | 85VA | 85W | 85W |
| | | 3200A、4000A | 110VA | 110W | 110W |
| | | 6300A | 150VA | 150W | 150W |
| Power supply voltage of intelligent controllers | | AC220V、AC380V、DC220V、DC110V | | | |
| Note: The reliable operating voltage range of the shunt release is 70%~110%, and that of the switching in electromagnet and operating mechanism is 85%~110% | | | | | |



The under-voltage release performance of a circuit breaker is shown in

table 9

| Type | | Under-voltage delay release | Under-voltage instantaneous release |
|---|-------------|---|-------------------------------------|
| Actuation time of the release | | Delay in 0.5, 1, 3, 5 and 10s | Instantaneous |
| Actuation voltage of the release | 35%~70%Us | Reliable switching out of the circuit breaker | |
| | ≤35%Us | Circuit breakers cannot be switched in | |
| | (85~110%)Us | Reliable switching in of the circuit breaker | |
| In 1/2 of delay time, if the power supply voltage restores to 85%Us | | The circuit breaker keeps switching out | — |
| Note: The accuracy of delay time is ±10% | | | |

Performance of auxiliary contacts

1. The conventional heating current of auxiliary contacts is 6A.

2. The forms of auxiliary contacts: The standard form is the 4-group switching contact, but different combining forms can also be supplied according to users' needs.

Shunt release

The circuit breaker can be switched out by remote operation.

table 10

| Rated working voltage Us(V) | AC380 | AC220 | DC220、110 |
|-----------------------------|-----------------------|-------|-----------|
| Actuation voltage (V) | (0.7~1.1)Us | | |
| Instantaneous current (A) | 0.7 | 1.3 | 1.3 |
| Switching out time | Not greater than 30ms | | |

Switching in electromagnet

When the energy storage is finished, the switching in electromagnet can instantaneously release the energy storage spring force that operates the mechanism, so that the circuit breaker can be quickly switched in.

table 11

| | | | |
|-----------------------------|-----------------------|-------|-----------|
| Rated working voltage Us(V) | AC380 | AC220 | DC220、110 |
| Actuation voltage (V) | (0.85~1.1)Us | | |
| Instantaneous current (A) | 0.7 | 1.3 | 1.3 |
| Switching out time | Not greater than 70ms | | |

Energy storage motor

The circuit breaker has motor-driven energy storage and automatic energy storage functions; manual energy storage is also available.

table 12

| | | | |
|-----------------------------|---------------------|-------|-----------|
| Rated working voltage Us(V) | AC380 | AC220 | DC220、110 |
| Actuation voltage (V) | (0.85~1.1)Us | | |
| Instantaneous current (A) | 192VA | | 192W |
| Switching out time | Not greater than 5s | | |

Rated values of auxiliary contacts

table 13

| Rated voltage (V) | | Conventional heating current Ith (A) | Rated control capacity |
|-------------------|-----|--------------------------------------|------------------------|
| AC | 230 | 6 | 300VA |
| | 400 | | |
| DC | 220 | | 60W |

○ Abnormal switching in and out capacity of auxiliary contacts

The switching out capacity of the auxiliary contacts under abnormal operating conditions according to operations

table 14

| Category of operation | Switching in | | | Switching out | | | Number of switching in and out cycles and operation frequency | | |
|-----------------------|--------------|------|---------------|---------------|------|---------------|---|--|------|
| | I/Ie | U/Ue | cos φ 或 T0.95 | I/Ie | U/Ue | cos φ 或 T0.95 | | | |
| AC-15 | 10 | 1.1 | 0.3 | 10 | 1.1 | 0.3 | 10 | 6 (or the same with the operating frequency of the main circuit) | 0.05 |
| DC-13 | 1.1 | 1.1 | 6Pe | 1.1 | 1.1 | 6Pe | | | |

Note: when Pe≥50W, the ceiling of T0.95 = 6Pe≤300ms

The switching in and out capacity of contacts under normal conditions

table 15

| Category of operation | Switching in | | | Switching out | | |
|-----------------------|--------------|------|---------------|---------------|------|---------------|
| | I/Ie | U/Ue | cos φ 或 T0.95 | I/Ie | U/Ue | cos φ 或 T0.95 |
| AC-15 | 10 | 1 | 0.3 | 1 | 1 | 0.3 |
| DC-13 | 1.1 | 1 | 6Pe | 1 | 1 | 6Pe |

Key lock at switching out position

The circuit breaker has a "key lock at switching out position" (supplied as ordered). It can lock the circuit breaker at the switching out position. At this moment, neither the switching in button nor the energy release (switching out) electromagnet switch in the circuit breaker.

6 Structure overview

Fixed circuit breakers are mainly composed of contact system, intelligent controller, manual operation mechanism, electric operation mechanism and installation board.

Withdrawable circuit breakers are mainly composed of contact system, intelligent controller, manual operation system, electric operation mechanism and drawer holder.

The circuit breaker adopts the three-dimensional layout, which is featured with compact structure and small volume. The contact system is enclosed in the insulating base, with the contact of each phase separated by insulating plates into small several chambers, while the intelligent controller, manual operation mechanism and electric operation mechanism separated into independent units sequentially in front of the contact system; if one unit is broken down, it can be independently removed and replaced by a new one.

A withdrawable circuit breaker consists of a plug-in circuit breaker and a drawer holder. The guide rails inside the drawer holder can be pulled in and out, and the circuit breaker is inserted on the guide rails for installation and removal, and the main circuit is connected through the connection of the busbar of plug-in circuit breaker with the bridge-type contact of drawer holder.

The withdrawable circuit breaker has 3 working positions: "connection" position, "test" position and "separation" position, and the change among three positions can be realized by screwing in or out the handle. The indications of each position are displayed by the pointer on the crossbeam of the drawer holder base.

When it is in the "connection" position, both the main circuit and the secondary circuit are turned on; when it is in the "test" position, the main circuit is turned off and separated by insulation board, and only the secondary circuit is switched on, making it possible to carry out some necessary action tests; when it is in the "separation" position, both the main circuit and the secondary circuit are turned off. Moreover, the withdrawable circuit breaker has a mechanically interlocking device, meaning the circuit breaker can be turned off only in the "connection" or "test" positions, and cannot be turned off in the positions between the "connection" and "test" positions.

※ The interlocking mechanism of circuit breaker (applicable for withdrawable type and fixed type). Users can solely use the interlocking mechanism to conduct the conversion of two or three units; users can also adopt our company's RNQ1 double power automatic switching equipment to realize the automatic switching of double-circuit power supply. Refer to the

product catalog for details.
Lever interlock

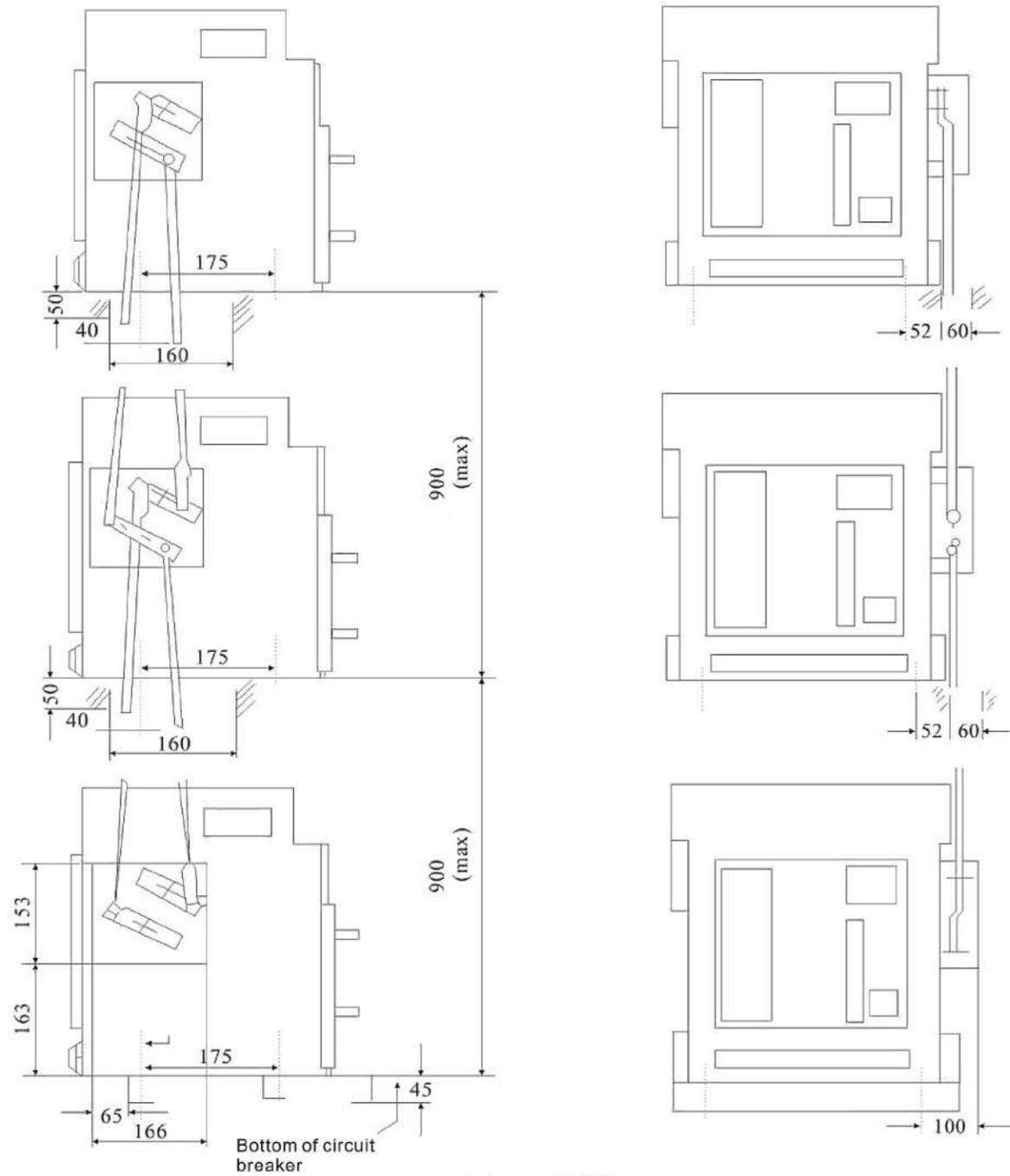


Figure 5 (A)

Three vertically mounted circuit breakers interlocked by the lever. If only 2 circuit breakers are interlocked, just remove the top circuit breaker.

Soft interlock (suitable for horizontal and vertical)

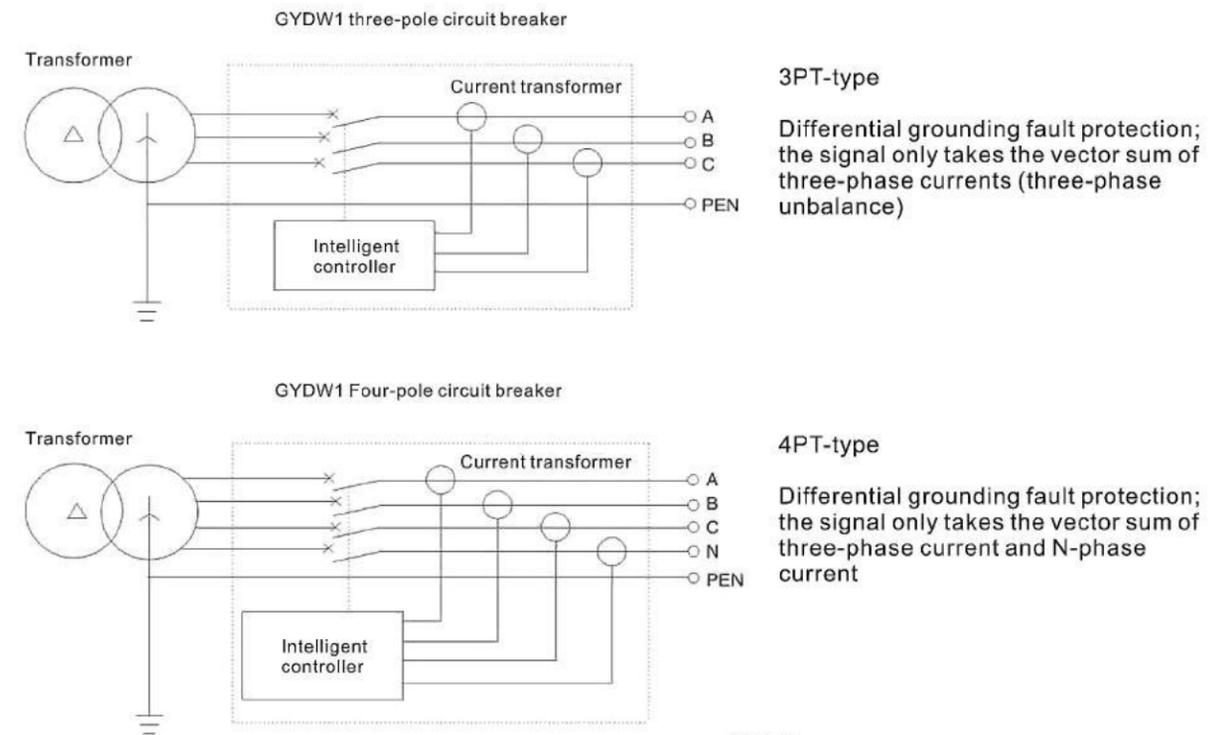


Figure 5 (B)

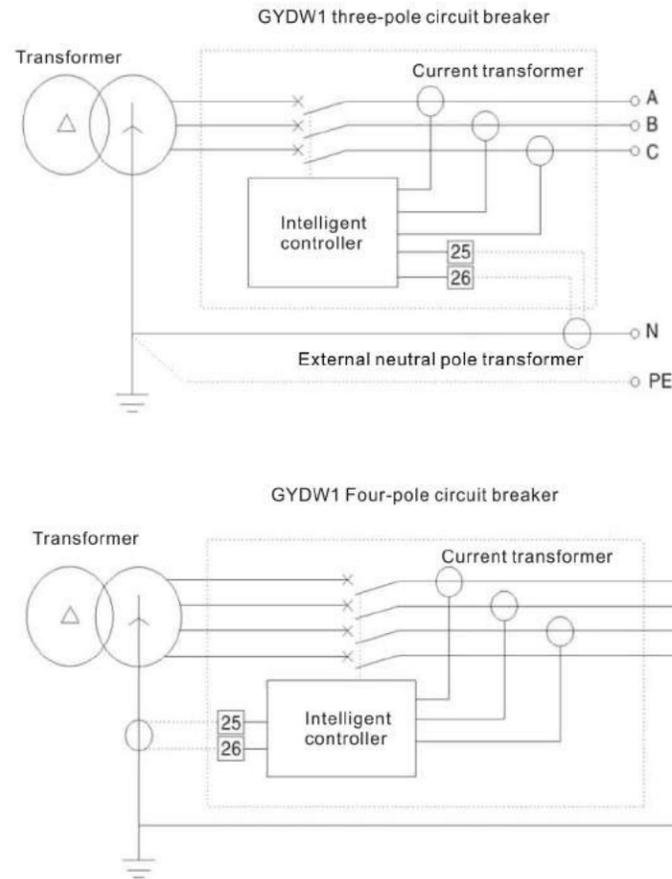
- ※Note: 1. If the steel wire rope needs to be bended, a transition arc of $R \geq 120\text{mm}$ at the bending position is compulsory to ensure the flexibility of the steel wire rope.
- 2. Check the steel wire rope and make sure it is well lubricated to ensure its flexibility.

7 Internal Wiring Mode

Protection circuit of grounding fault



图六(A)



(3P+N)T-type
Differential grounding fault protection; the signal only takes the vector sum of three-phase current and N-phase current

(3P+N)W-type
External grounding current transformer
Ground current type grounding fault protection; the signal is taken directly between the neutral point of power supply and the ground

Figure 6 (B)

External single phase grounding protection function

The external transformer (neutral pole transformer or current transformer) is supplied to the user as an accessory. Users to install it into the busbar, and connect it cable (2m long) to the secondary wiring terminals #25 and #26 of the circuit breaker.

The center holes (the maximum allowable size through busbar) of the external transformer

| Model | Width | Height |
|---|-------|--------|
| GYDW1-2000 GYDW1-4000/4 | 61 | 21 |
| GYDW1-3200 and above (Except GYDW1-4000/4) | 87 | 31 |

Wiring terminal

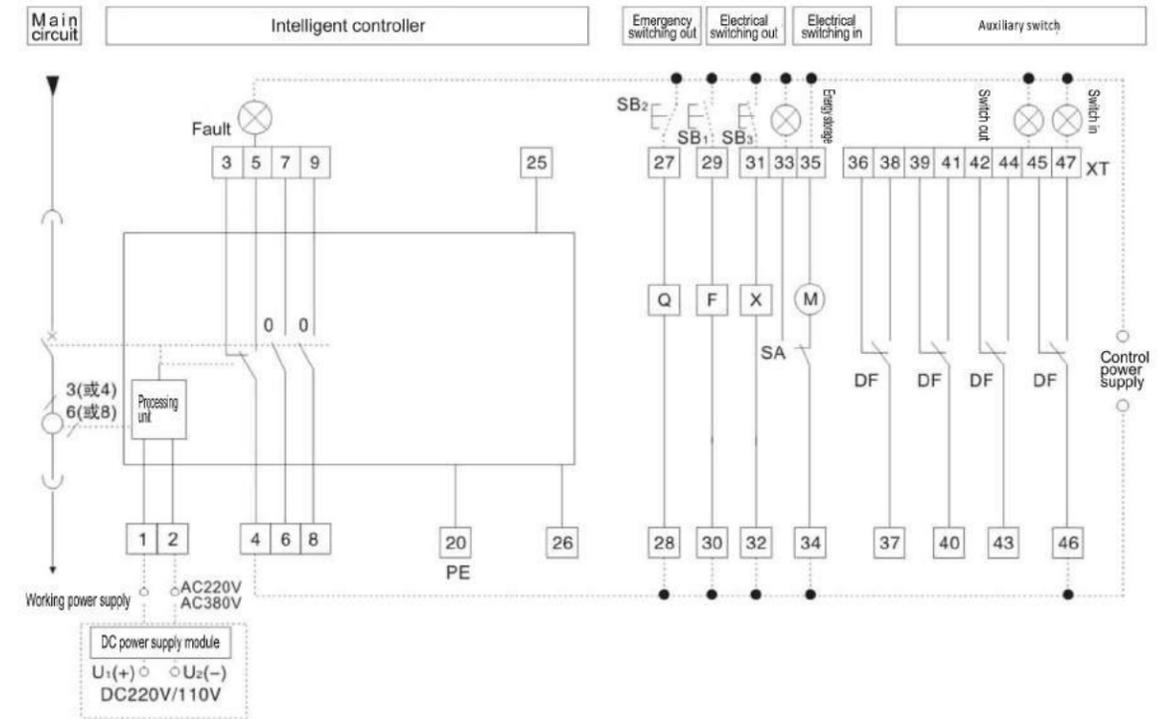
There are 47 wiring terminals in total on the circuit breaker, making it convenient for users' wiring operation; see Figure 7a, 7b and 7c for wiring diagrams

○ Figure 7a (the controller is M-type or L-type with basic functions)

Other wirings of the intelligent controller

#1, #2 Input terminals of operating power

#25, #26 Input terminals of external neutral pole or underground current transformer



□Note:

- (1) If the F, X and M have different controlling supply voltages, they should be connected with different power supplies respectively.
 - (2) The terminal #35 can be directly connected with the power supply (automatically pre-storing energy), and can also be connected with the power supply after connected in serial with normally open button (manually pre-storing energy).
 - (3) If required by users, the terminals #6~#7 can output the normally closed contacts.
 - (4) Additional accessories are prepared by users.
 - (5) When DC power supply is used as the working power supply of the intelligent controller, the conventional configuration adopts a "built-in" (not specified by users) DC power supply module, and terminals #1 and #2 can be directly connected to the DC power supply, but DC power supply must be input through DC power supply modules U1(+) and U2 (-); two output terminals of the DC power supply module are connected to the secondary wiring terminals 1(+) and 2(-), respectively.
- SB1 Shunt button (prepared by users), X Switching in electromagnet, DF Auxiliary contact, Q Under-voltage release or under-voltage delay release
SB2 Under-voltage button (prepared by users), M Energy storage motor, F Shunt release, O Normally open contact (3A/AC380V)
Sb3 switching in button (prepared by users), XT Wiring terminal, SA Motor micro-switch / Signal light (prepared by users)

○ Figure 7b (the controller is L-type or M-type with additional functions)

Other wirings of the intelligent controller

Terminals #1 and #2 are the input terminals of AC working current

#12, #13 and #14, #15 and #16, #17 and #18, #19 Four sets of signal contacts, respectively; see Table 17 for the output function.

#20 Protective grounding

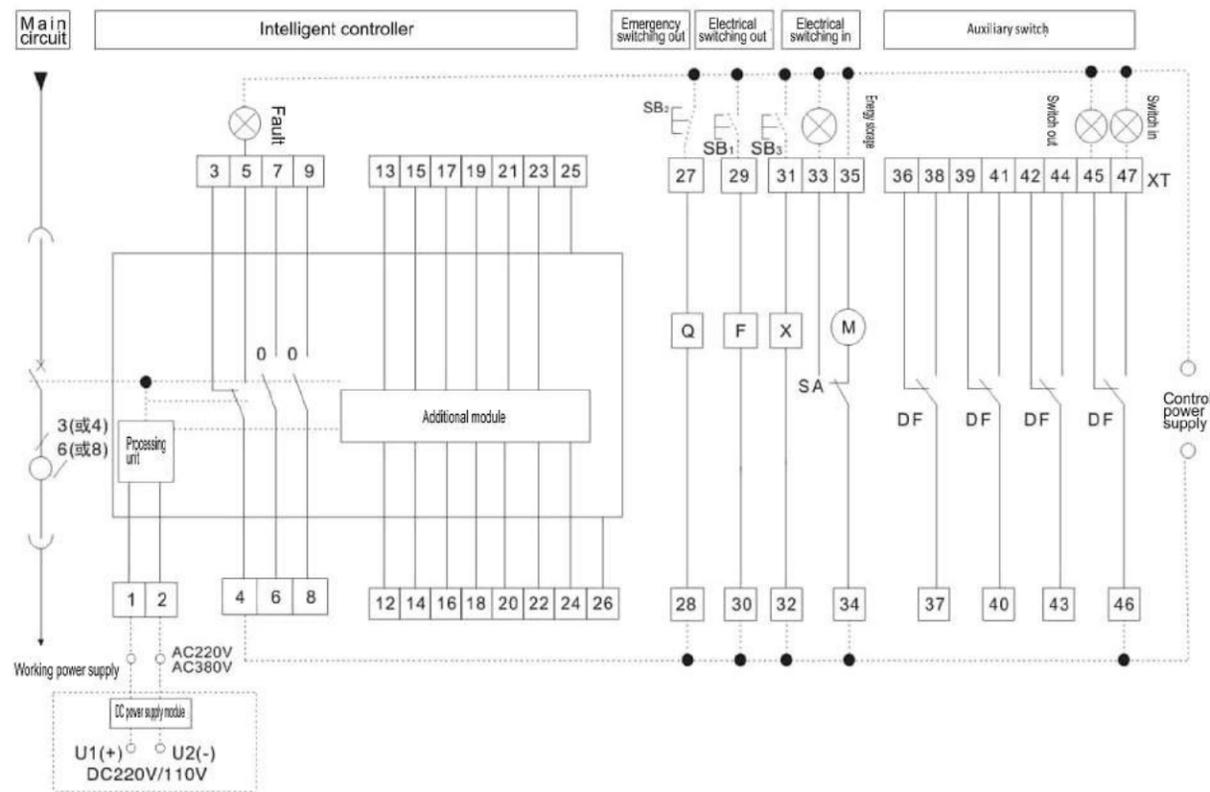
#21 N-phase

#22 A-phase Voltmeter function voltage input end

#23 B-phase

#24 C-phase

#25, #26 Input terminals of external neutral pole or underground current transformer



Note:

- (1) If the F, X and M have different controlling supply voltages, they should be connected with different power supplies respectively.
- (2) The terminal #35 can be directly connected with the power supply (automatically pre-storing energy), and can also be connected with the power supply after connected in serial with normally open button (manually pre-storing energy).
- (3) If required by users, the terminals #6~#7 can output the normally closed contacts.
- (4) Additional accessories are prepared by users.

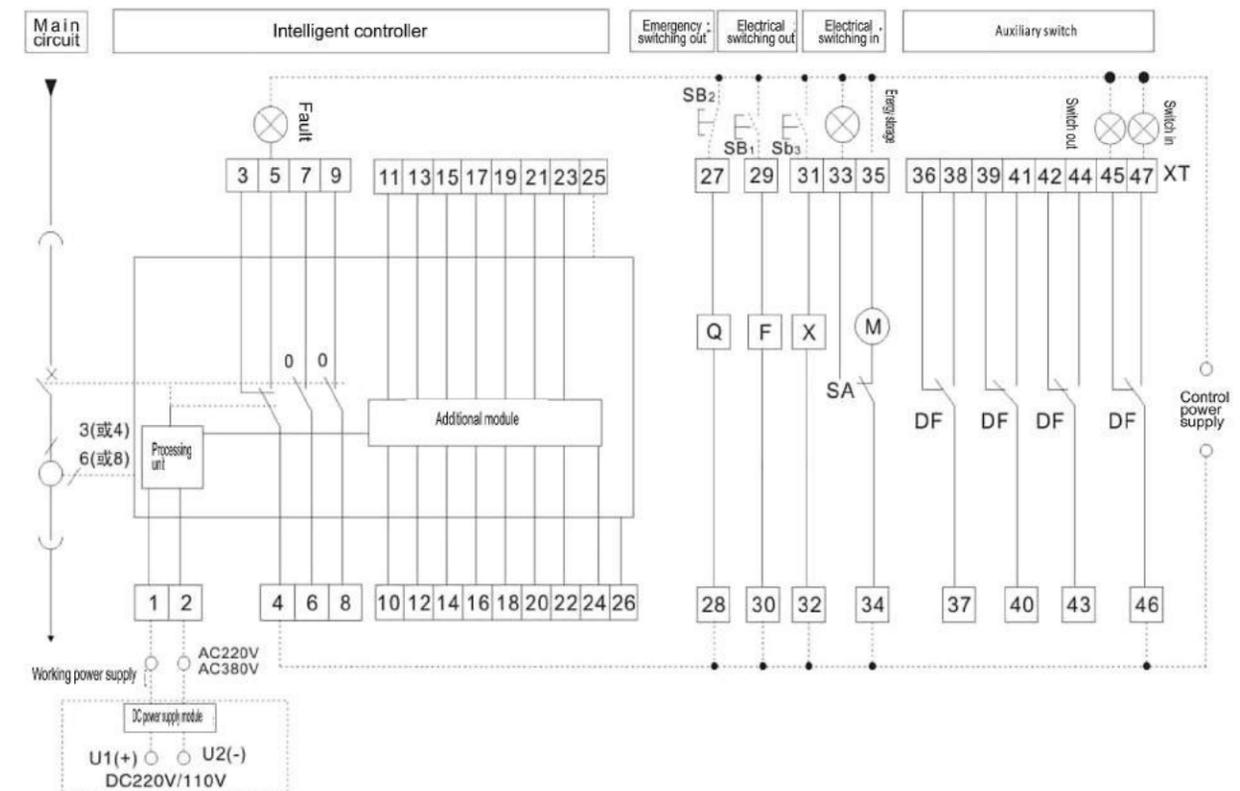
(5) When DC power supply is used as the working power supply of the intelligent controller, the conventional configuration adopts a "built-in" (not specified by users) DC power supply module, and terminals #1 and #2 can be directly connected to the DC power supply. If users adopt "external" DC power supply module, terminals #1 and #2 must not directly connected to the DC power supply which should be input through DC power supply modules U1(+) and U2 (-); the two output terminals of the DC power supply module are connected to the secondary wiring terminals 1(+) and 2(-), respectively.

SB1 Shunt button (prepared by users), X Switching in electromagnet, DF Auxiliary contact, Q Under-voltage release or under-voltage delay release

SB2 Under-voltage button (prepared by users), M Energy storage motor, F Shunt release, O Normally open contact (3A/AC380V)

Sb3 switching in button (prepared by users), XT Wiring terminal, SA Motor micro-switch / Signal light (prepared by users)

○ Figure 7c (the controller is H-type)



Other wirings of the intelligent controller

Terminals #1 and #2 are the input terminals of AC working current

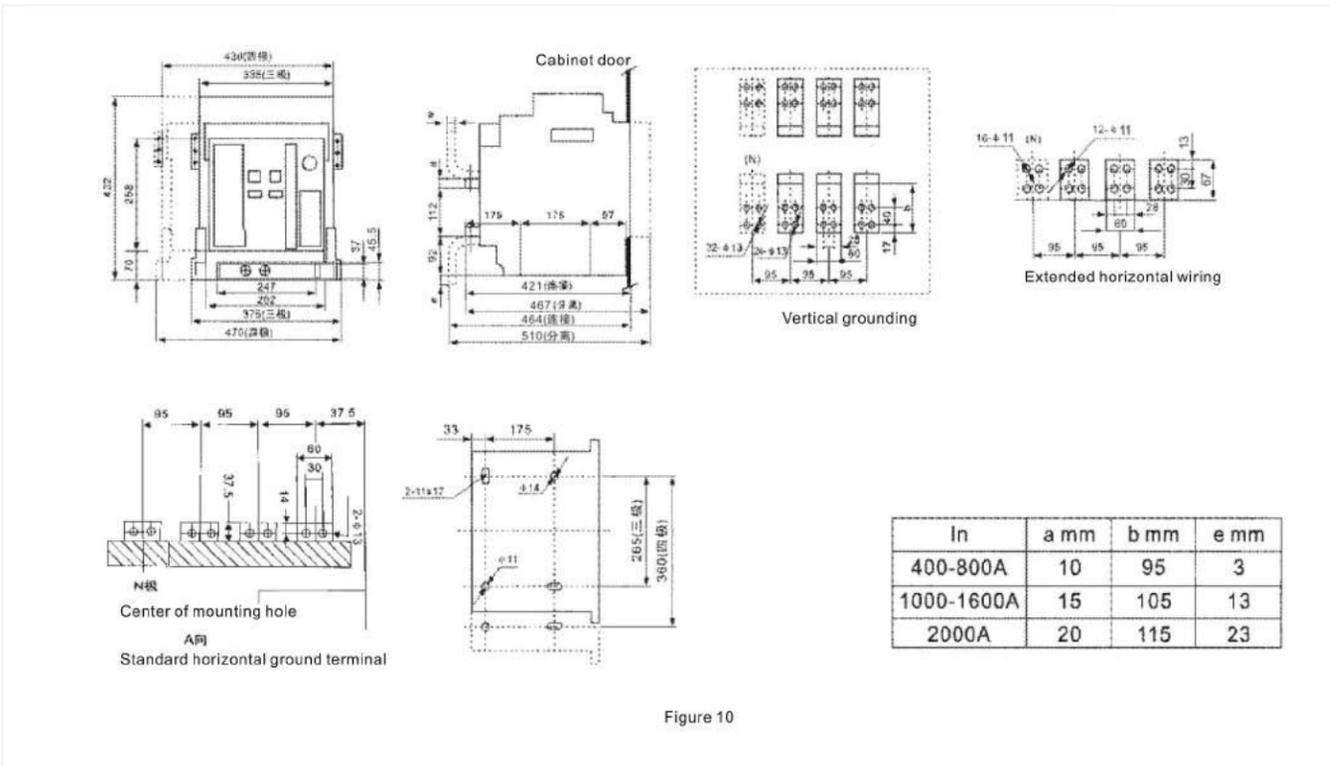
#10, #11 A and B ends of RS485 communication interface lead-out wire

#12, #13 and #14, #15 and #16, #17 and #18, #19 Four sets of signal contacts, respectively; see Table 17 for the factory default states of output functions.

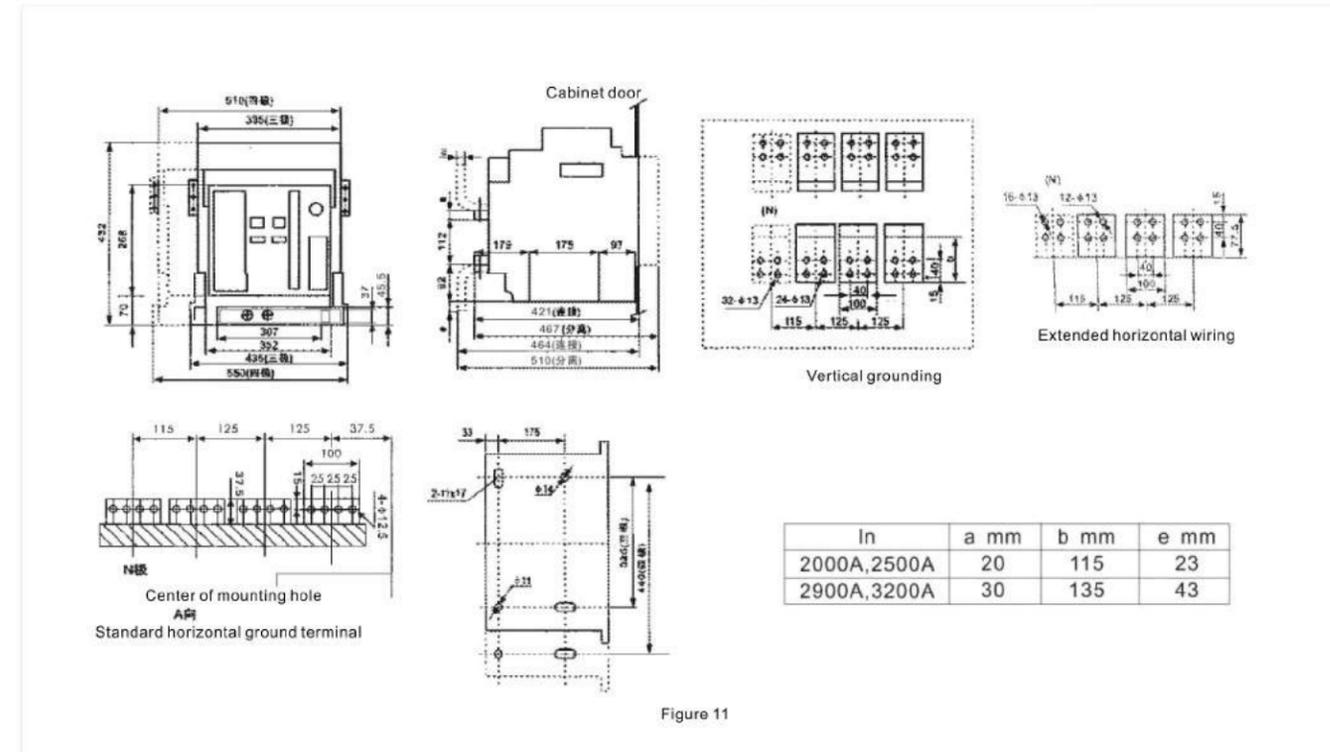
#20 Protective grounding

Installation dimensions and overall dimensions of withdrawable circuit breakers

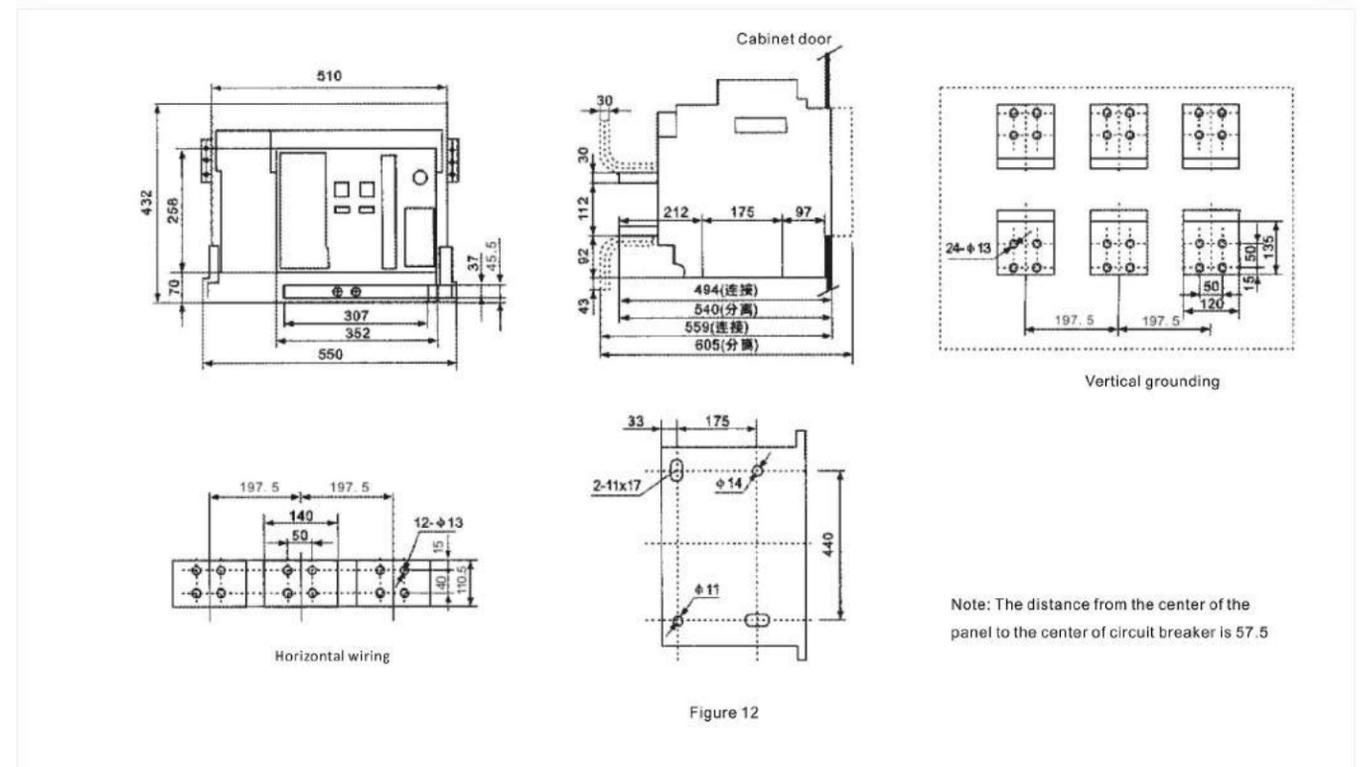
See Figure 10 for the installation dimensions and overall dimensions of (GYDW1-2000, 2000/4) withdrawable circuit breakers



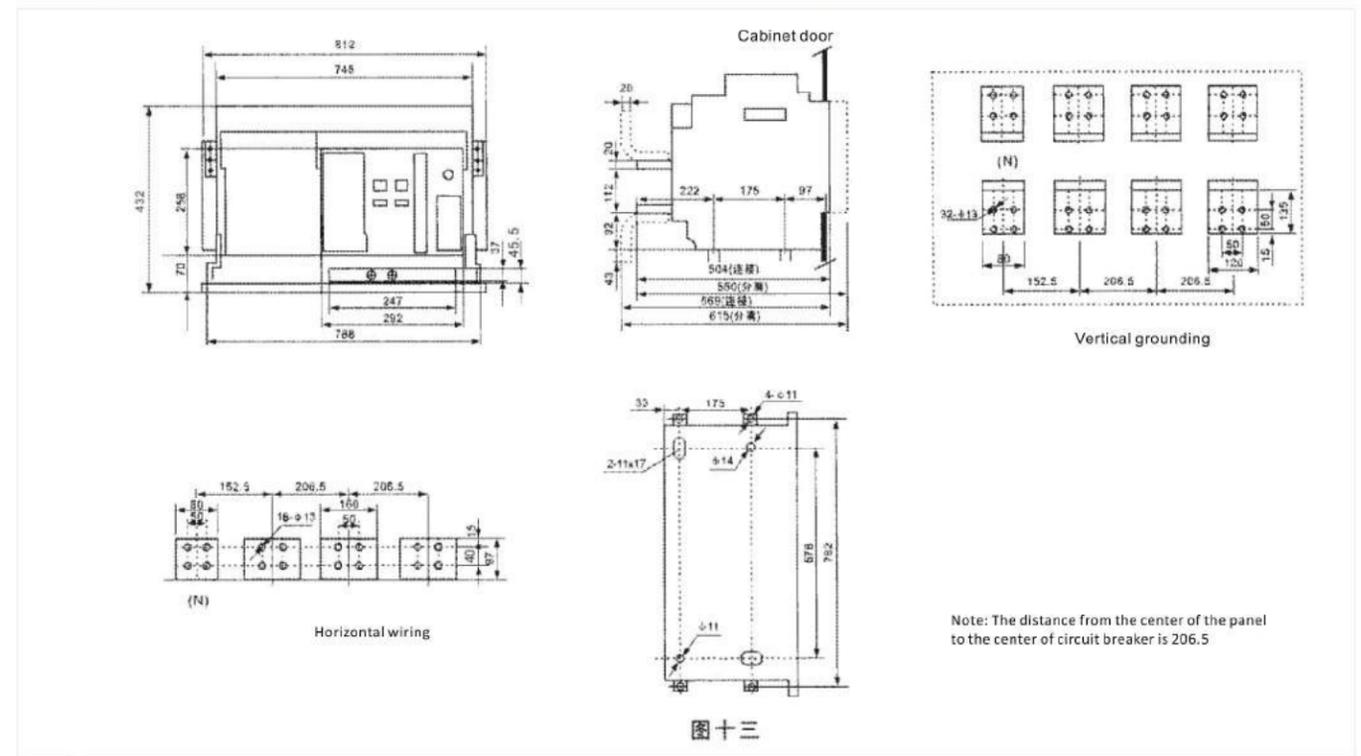
See Figure 11 for the installation dimensions and overall dimensions of (GYDW1-3200, 3200/4) withdrawable circuit breakers



See Figure 12 for the installation dimensions and overall dimensions of (GYDW1-4000) withdrawable circuit breakers



See Figure 13 for the installation dimensions and overall dimensions of (GYDW1-4000/4) withdrawable circuit breakers



See Figure 14 for the installation dimensions and overall dimensions of (GYDW1-4000) fixed circuit breakers

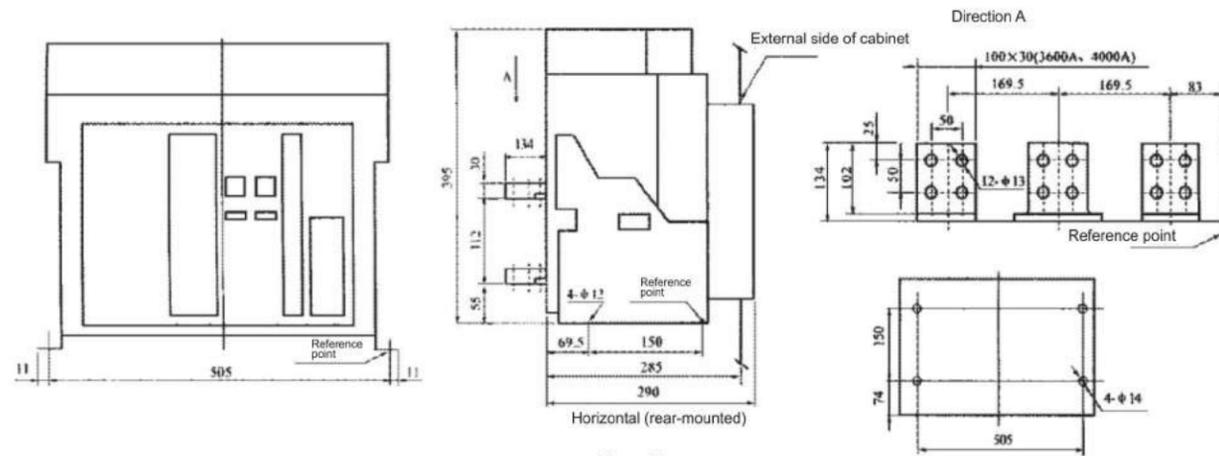


Figure 14

See Figure 15 for the installation dimensions and overall dimensions of (GYDW1-4000/4) fixed circuit breakers

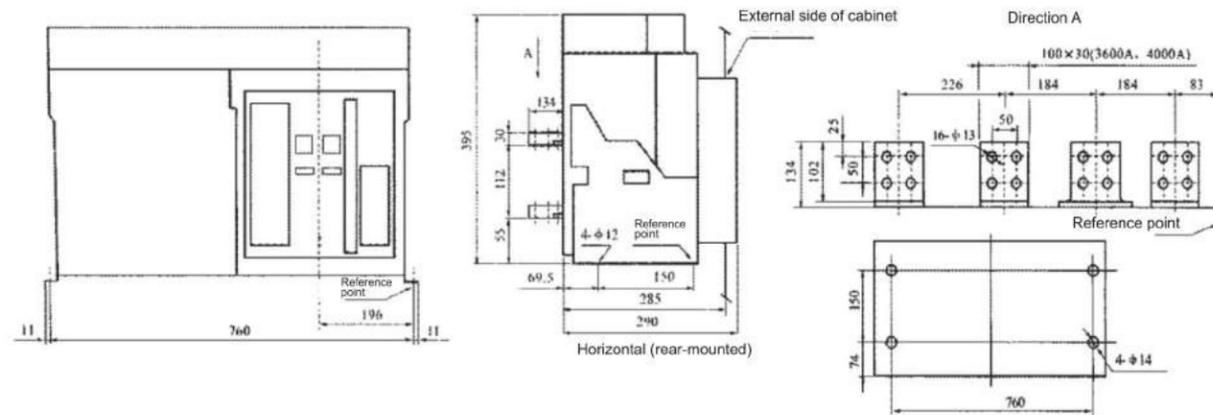


Figure 15

See Figure 16 for the installation dimensions and overall dimensions of (GYDW1-5000) fixed circuit breakers

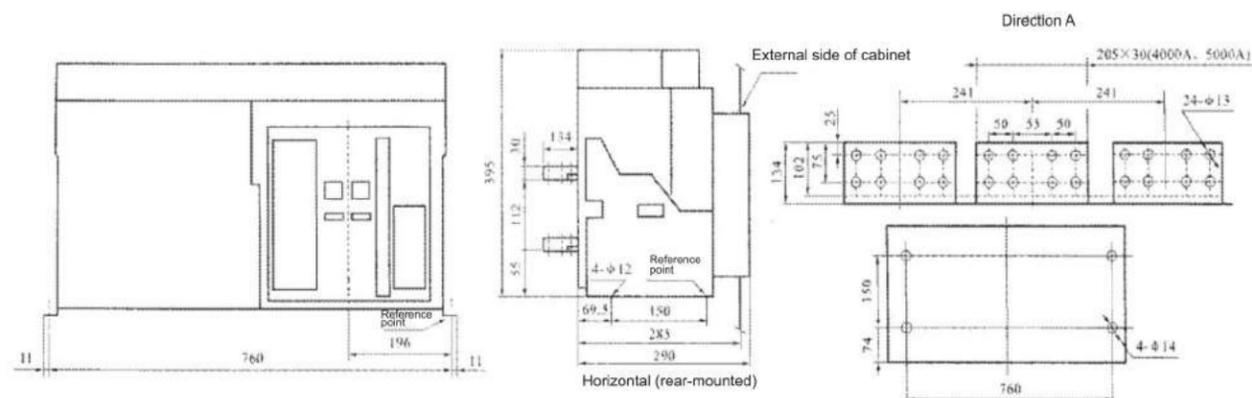


Figure 16

See Figure 17 for the installation dimensions and overall dimensions of (GYDW1-6300, 6300/4, In=4000, 5000) withdrawable circuit breakers

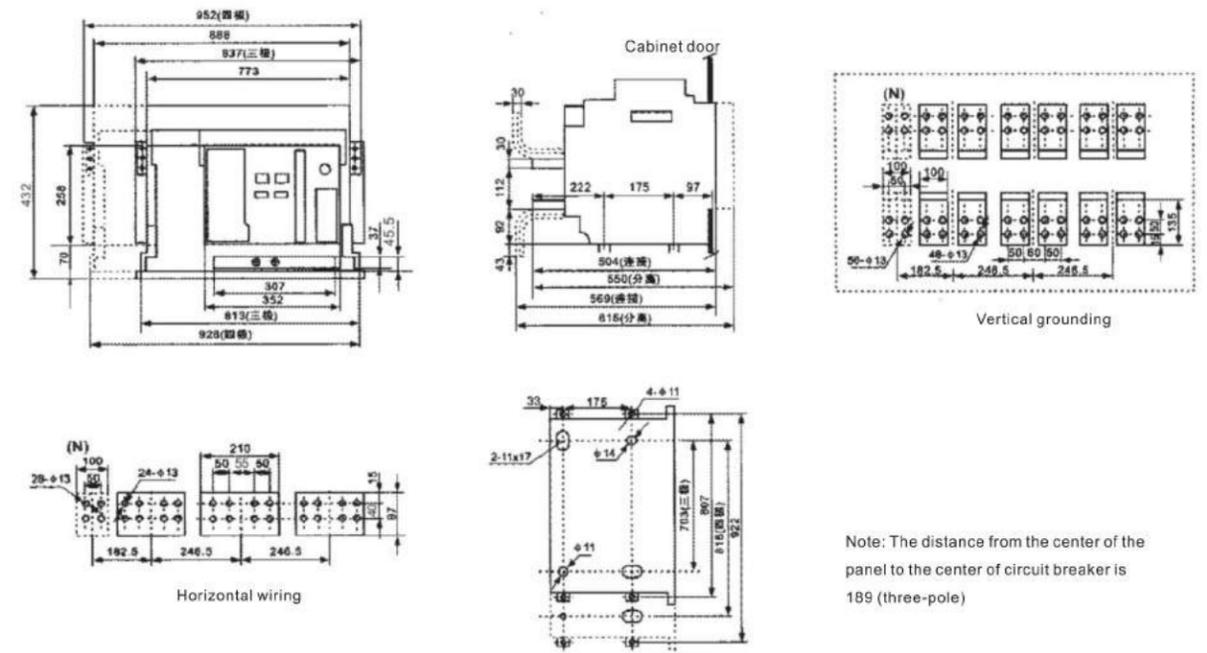


Figure 17

See Figure 18 for the installation dimensions and overall dimensions of (GYDW1-6300, In=6300A) withdrawable circuit breakers

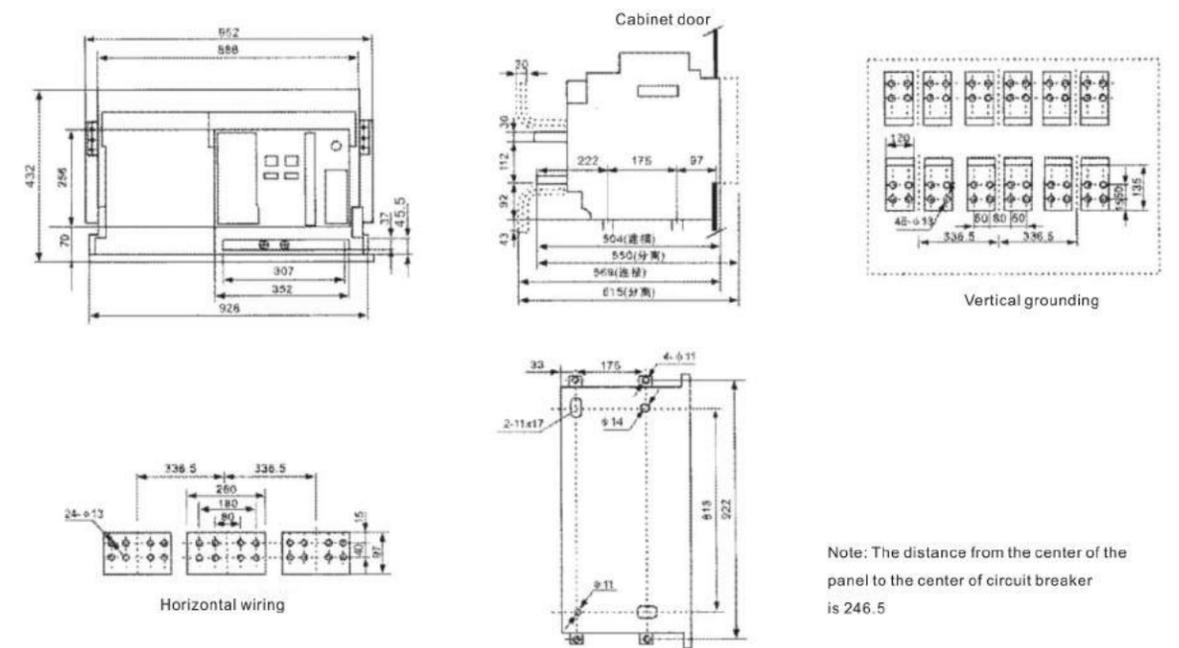
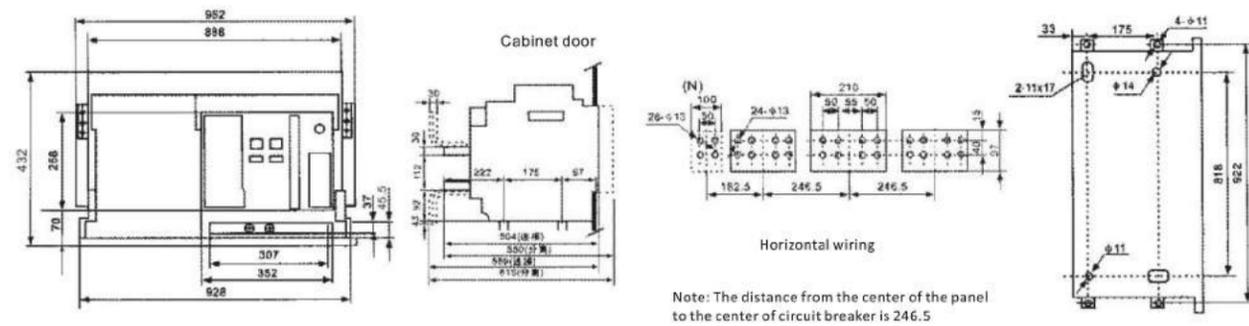


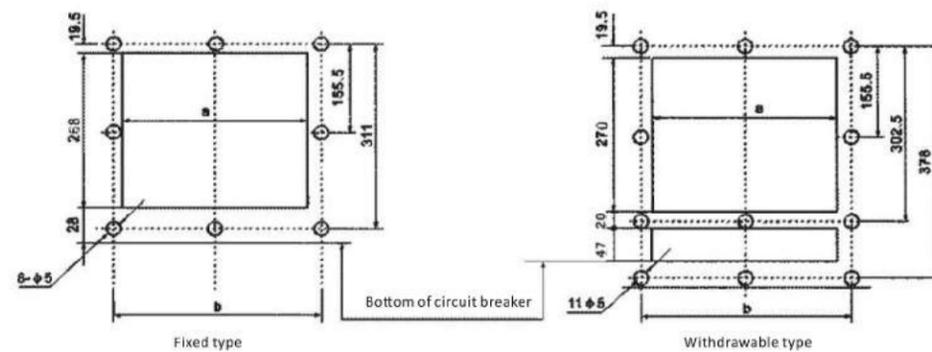
Figure 18

See Figure 19 for the installation dimensions and overall dimensions of (GYDW1-6300/4, In=6300A) withdrawable circuit breakers



| Rated current | External copper busbar specifications | Pieces per pole | Rated current | External copper busbar specifications | Pieces per pole |
|---------------|---------------------------------------|-----------------|---------------|---------------------------------------|-----------------|
| 630A | 40×5 | 2 | 2900A | 100×10 | 3 |
| 800A | 50×5 | 2 | 3200A | 120×10 | 3 |
| 1000A | 60×5 | 2 | 3600A | 120×10 | 4 |
| 1250A | 80×5 | 2 | 4000A | 120×10 | 4 |
| 1600A | 80×6 | 2 | 5000A | 120×10 | 5 |
| 2000A | 80×8 | 2 | 6300A | 120×10 | 6 |
| 2500A | 100×10 | 2 | | | |

9 Dimensions and mounting holes spacing of door frame



| Inm | a mm | b mm |
|-------------|------|------|
| 2000 | 302 | 345 |
| 3200、4000/3 | 362 | 405 |
| 4000/4 | 302 | 345 |
| 6300 | 362 | 405 |

10 Installation, operation and maintenance

Installation

1. Before installation, check whether the specification of the circuit breaker meets relevant requirements.
2. Before installation, check the insulation resistance of the circuit breaker with a 500V megohmmeter, and the resistance shall not be less than 10MΩ when the temperature of the surrounding medium is 20±5°C and the relative humidity is 50%~70%. Otherwise, the surrounding medium should be dried until the insulation resistance reaches the requirement.
3. During the installation of circuit breaker, its base shall be in horizontal position and fixed with M10 screws.
4. During installation, the circuit breaker should be reliably grounded for protection, and the grounding position should have an obvious mark.
5. Either upper or lower incoming feeder is adopted, its technical performance remains unchanged.
6. After the installation and wiring according to relevant wiring diagrams, the following operations and tests should be carried out before the main circuit is energized (the pointer on the drawer holder of the withdrawable circuit breaker is at the "test" position).

- 1) Check the under-voltage, shunt release and energy releasing (switching in) electromagnet and the voltage of electrically operated mechanism meet relevant requirements (before the circuit breaker switching in, the under-voltage release must be energized).
- 2) Pull the handle on the shell up and down for 7 times, then the panel displays "storing energy", and after hearing a "click" sound, the energy storage is finished; press "I" button or energy release (switching in) electromagnet, and the circuit breaker is reliably switched in (in case of the controller reset button is reliably reset); pulling the handle can store energy again.
- 3) Turn on the motor and the panel displays "storing energy", and after hearing "click" sound, the energy storage is finished, then the motor is automatically turned off; press the "I" button or energy release (switching in) electromagnet, and the circuit breaker is reliably switched in.
- 4) After switching in the circuit breaker, whatever the under-voltage, shunt release or "O" button, or the release tests of the intelligent controller shall be able to switch out the circuit breaker.

○ Applications of intelligent controllers

Controller setting

Long delay current setting of the controller: After pressing the "clearing light" button, hold pressing the "setting" button until the long delay indicator light becomes bright and the panel displays factory long delay current setting value, which is generally I_n ; current setting range is $(0.4\sim1.0)I_n$, and press the "+" and "-" buttons to adjust the current close to required value; each time you press the button, the current changes with an interval of <2%. Then press the "storage" button and the storage indicator light blinks once, indicating the long delay current setting value has been stored.

Long delay time setting: After setting the long delay current, press the "setting" button once more and the long delay state indicator light becomes bright and the panel displays the factory long delay setting; pressing the "+" button once doubles the time, while pressing the "-" button once reduces the time by half; after adjusting the time to required value, press the "storage" button once, then the storage indicator light blinks once, indicating the long delay setting being finished. The setting and of load monitoring, short delay, instantaneous, grounding and other protection action values and action time can be achieved by the above-mentioned methods, only with different indication states. If the grounding time is set in the "OFF" position, it indicates a fault state, and grounding fault only alarms rather than releasing; if instantaneous setting is in the "OFF" position, it indicates cancelling the protection; during setting process, if there is any fault signal, the controller automatically lock other functions and enter the fault handling state.

The setting values of various protection parameters should not be intersected. The protection priority of the controller is as follows: Long delay < short delay < instantaneous. For re-switching in, the setting value of ILc2 is smaller than that of ILc1, and after setting all the parameters of the controller, press again the "clear light" button or reset the controller by re-connecting the power supply, so as to keep the controller in running state.

Controller test

After setting the parameters of the controller and before operating the circuit breaker, users can check various protective functions of the controller according to their requirements; the controller tests have the option of release/un-release, and pressing the "release" button will switch out the circuit breaker, and pressing the "un-release" will not send the releasing signal, therefore, the circuit breaker will not be switched out. (L-type circuit breaker only has releasing test. Press the "test" button for one time, and the controller generates an instantaneous signal to switch out the circuit breaker).

Overload test: Press the "setting" button to enter the long delay state, then check the overload setting value and then other current states; press the "+" and "-" buttons to set the current to >1.3Ir1, then press the "test" button to enter the overload test state, and the controller actuates with time delay in inverse time-lag, and indicates the fault type and test state. Other characteristic tests are carried out in similar procedures; after tests, press the "clear light" button to enter normal running state, and meanwhile the mechanical "reset" button must be pressed at the same time, then the circuit breaker can be switched in.

Other operating rules of the controller

When the controller is in setting and checking states, if no button is pressed within 1 minute, the controller will automatically clear the buttons and enter the running state; at the same time, if there is any fault, the controller will automatically block other functions and enter the fault handling state.

1. Check setting

After the controller "clearing the lights", if there is no fault, continuously pressing the "setting" button can circularly indicate various states and corresponding setting current and time values. After checking, press the "clearing light" button (if no button is pressed within 1 minute, controller will automatically enters the normal running state).

2. Check power grid operating current and voltage

After the controller "clearing lights", if there is no fault, continuously press the "select 1" ("select") button to circularly indicate the operating currents of each phase as well as the grounding current value, and the current of the max. phase is normally displayed; continuously press the "select 2" button to circularly indicate the voltages of each circuit, and the voltage of the max. circuit is normally displayed.

After the controller "clearing the lights", press the "fault check" button to display the state and current of the fault happened last time, and after test or fault releasing, press the "select 1" ("select") button can circularly display test or fault current or time values. The test state is not stored.

3. Resetting

Before switching the circuit breaker, the "clear light" button of the controller must be pressed at first to make the controller entering normal running state, and press the mechanical "resetting" button, then the circuit breaker can be switched in.

If users have any specific requirement based on Table 4, Table 5 and Table 6, they can put forward the requirements in their orders, and corresponding parameters will be set according to the orders before delivery.

If there is specific requirement in users' orders, parameters of the controller will be set to default values, as shown in Table 18.

| Load monitoring | Long delay protection | Short delay | Instantaneous protection | Grounding protection |
|-----------------|---------------------------------|-------------|-----------------------------------|--|
| IC1=In | Ir1=In | Ir2=8Ir1 | Ir3=10In (L型) Ir3=12Ir1 (M、H型) | Inm=2000A (0.4In) Inm=3200~4000A (0.2In) Inm=6300A (0.4In) |
| IC2=In | tL=60s (L、M型) tL=26.66s (H型) | tS=0.4s | — | tG=OFF |

Note: The protection long delay setting value of the motor is 1.25In, and constant time-lag short delay protection is turned off.

During operation, users need to change the factory setting value. After fully understanding the product, customers are allowed to set up the controller by themselves according to Table 4.

○ The panel layout of M-type (standard type) intelligent controller is as shown in Figure 20

- 1- Resetting button. After releasing, it is necessary to press the resetting button before again switching in the circuit breaker.
 - 2- Current and time display, it displays current or time values.
 - 3- "Select" button. In the normal running state, pressing it can display the currents in various phases; in the fault state or fault checking state, pressing it can display fault current or time values.
 - 4-LED light indication. It can indicate various states and types.
 - 5- "Clear light" button. This button must be pressed after controller setting and fault testing or before switching in the circuit breaker, so as to make sure the release is in normal operating state.
 - 6- "Setting" button. This button is used to check or set various protection characteristic current or time values. Press this button can circularly indicate various states.
 - 7- "Fault check" button. After the controller "clearing lights", pressing this button can display and indicate the state, current and time values of the fault happened last time. The fault current or time is circularly checked by pressing the "select" button.
 - 8- "Display check" button.
 - 9- "Release" and "Un-release" buttons. The two buttons are used in simulation tests.
 - 10- "Storage", "+" and "-" buttons. Used for setting current and time.
- Ir4- Grounding protection current setting value.
 Ir1- Long delay current setting value.
 Ir2- Short delay current setting value.
 Ir3- Instantaneous current setting value.
 tG- Grounding protection time setting value.
 tL- Long delay time setting value.
 tS- Short delay time setting value.

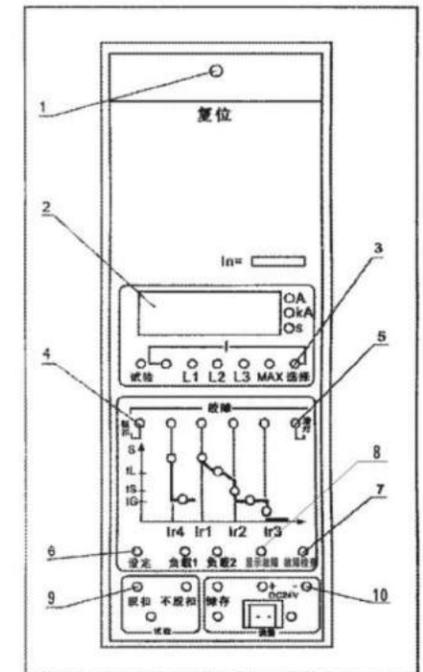


Figure 20

○ The panel layout of H-type (communication type) intelligent controller is as shown in Figure 21

- 1- Resetting button, 2- Voltage display, 3- Power and voltage unit, 4- Parameter display screen, 5- Three-phase current display
- 6- Circuit breaker switching out times, 7- Unbalance rate, 8- Current and time, 9- Grounding current and time indication
- 10- Long delay current and time indication, 11- Short delay current and time indication, 12- Instantaneous current indication
- 13- Self-diagnostic fault indication, 14- Fault release indication, 15- Fault alarm indication, 16- Setting value storage indication
- 17- Confirm button, 18- Return key, 19- Communication signal sending and receiving indication, 20- state and authority position lock
- 21- Status function select button, 22- Function up-turning and setting value ascending button, 23- Function down-turning and setting value descending button
- 24- Current and time setting states indication, 25- Fault inquiry state indication, 26- Test state indication
- 27- Load 1 current and time indication, 28- Load 2 current and time indication, 29- N-phase indication, 30- Unbalance rate and time indication

Basic functions:

1. Overload long delay, short-circuit short delay, and short-circuit instantaneous protection
2. Grounding fault protection
3. Load monitoring protection
4. Various states indications and value display
5. Ammeter function
6. Voltmeter function
7. Fault memory function
8. Thermal memory function
9. Test function
10. RS485 serial interface

Optional functions

- 1) MCR switching in and out [MCR switching in and out protection, only working at the switching in moment (within about 100ms) of the circuit breaker].
2. Alarm or fault state indications. Among the 4 sets of remote output signal units, the first and the second sets can output according to users' needs, and the third set of signals are remote control switching in signals, and the fourth set of signals are remote control switching out signals.

Figure 21

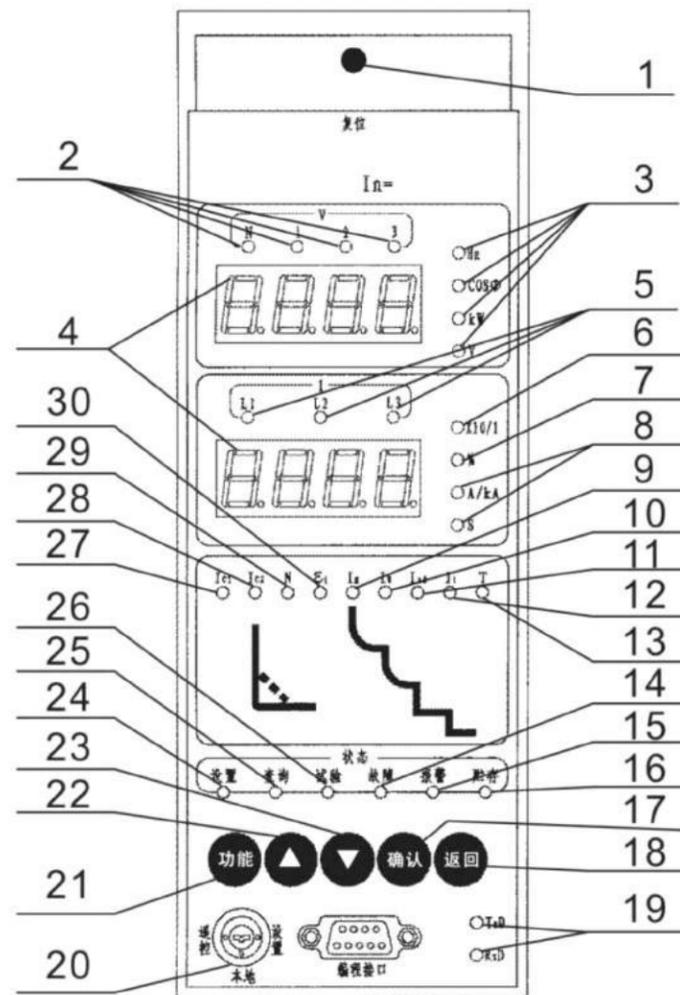


Figure 21

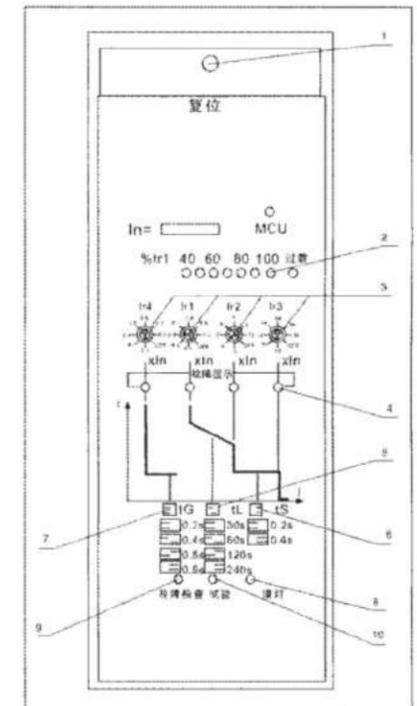
○ The panel layout of L-type (economic type) intelligent controller is as shown in Figure 21

- 1- Resetting button. After the circuit breaker fault and the test releasing, the circuit breaker can be switched in again only after pressing this button.
2. Load display. It displays overload long delay current.
3. The setting knob for long delay, short delay, instantaneous and grounding protection currents. Each protection current can be set according to the scale value on the knob.
4. Fault indicator light. It indicates the fault type.
5. Long delay overload protection time setting button. Toggle the switch position to adjust time.
6. Short delay protection time setting button. Toggle the switch position to adjust time.
7. Grounding fault protection time setting value. Toggle the switch position to adjust time.
8. Clear light button. After controller setting, testing and fault, this button must be pressed to make the controller entering normal operating state.
9. Fault check button. After the circuit breaker switching out due to faults, pressing this button can indicate the cause of fault tripping. The circuit breaker has a fault memory function even in case of power failures.
10. Test button. Pressing this button can check the cooperating conditions of the controller and the circuit breaker.

○ The setting method of L-type circuit breaker

1. Long delay setting
 - 1) Rotate Ir1 switch to set the current from (0.4~1)In.
 - 2) Toggling the "tL" button can set the time to 30s, 60s, 120s and 240s.
 - 3) If the Ir1 switch is rotated to the OFF position, it indicates exiting this function.
2. Short delay setting
 - 1) Rotate Ir2 switch to set the current from (3~10)In.
 - 2) Toggling the "tS" button can set the current to 0.2s and 0.4s.
 - 3) If the Ir2 switch is rotated to the OFF position, it indicates exiting this function.
3. Instantaneous current setting
 - 1) Rotate Ir3 switch to set the current from (10~20)In or (7~14)In.
 - 2) If the Ir3 switch is rotated to the OFF position, it indicates exiting this function.
4. Grounding fault protection setting
 - 1) Rotate Ir4 switch to set the current from (0.2~0.8)In.
 - 2) Toggling the "tG" button can adjust the current to 0.2s, 0.4s, 0.6s and 0.8s.
 - 3) If the Ir4 switch is rotated to the OFF position, it indicates exiting this function.
5. The controller enters the operating state. After setting all parameters of the controller, it is necessary to press the "clear light" button.

Figure 22



Common faults and solving measure

| No. | Description of fault | Causes | Solving methods |
|-----|---|---|---|
| 1 | Circuit breakers cannot be switched in | Under-voltage release is not energized, without supply voltage. After the controller actuating, the red button on the upper panel of the controller panel is not reset. The operating mechanism has not stored energy. The withdrawable body has not been put in the "connecting" or "testing" position The "switching out position key lock" is in switching out state | Check the circuit and switch in the under-voltage release current. Pressing the resetting button Manually or electrically store energy in the mechanism Move the circuit breaker to the "connecting" or "testing" position by rotating the handle Switch in the key lock with a special key |
| 2 | The circuit breaker cannot store energy electrically | The power supply of electrically operated mechanism is not connected Insufficient power capacity | Check the circuit and switch on the power supply Check the operating voltage which should be greater than 85%Us |
| 3 | Closing the electromagnet does not switch in the circuit breaker | No supply voltage Insufficient power capacity The normally closed auxiliary contact is obstructed | Check the circuit and switch on the power supply Check the operating voltage which should be greater than 85%Us Check the states of contacts or adjust the auxiliary over position |
| 4 | The shunt release cannot switch out the circuit breaker | No supply voltage Insufficient power capacity After switching in, the auxiliary contact is not connected | Check the circuit and switch on the power supply Check the operating voltage which should be greater than 70%Us Check the states of contacts or adjust the auxiliary over position |
| 5 | Fault currents exceed long delay, short delay and instantaneous setting values and there are only instantaneous actions; no short delay and long delay actions. | The settings of long delay, short delay and instantaneous values are not proper, as they are set within the same current range. | Following the principle of $I_{r1} < I_{r2} < I_{r3}$ and considering the range of actions, reset the current values |
| 6 | Frequent tripping of the circuit breaker | Overload operation triggers overload protection tripping, and the circuit breaker is switched in again due to the overload thermal memory function fails to clear the fault by re-connecting the power supply in time. | Re-connect the power supply of the controller, or re-switch in the circuit breaker in 30min |
| 7 | The handle of withdrawable circuit breaker cannot be inserted into the circuit breaker | The withdrawable guide rail or circuit breaker body has not been completely pushed inside | Push the guide rail or circuit breaker body to the bottom |
| 8 | At the switching out position, the body of withdrawable circuit breaker cannot be pulled out from the holder | The handle has not been pulled out The circuit breaker does not completely reach the "separation" position | Pull out the swing handle Swing the handle to move the circuit breaker completely to the "separation" position |

11 Specifications of ordering

(please mark in the , or fill in numbers)

| Order unit | Order quantity | Order date | | |
|---|---|--|---|--|
| Model <input type="checkbox"/> GYDW1-2000[II frame] <input type="checkbox"/> Fixed type <input type="checkbox"/> Class III Nominal voltage Ue <input type="checkbox"/> AC400V <input type="checkbox"/> AC690V <input type="checkbox"/> GYDW1-3200[II frame] <input type="checkbox"/> Withdrawable <input type="checkbox"/> Class IV Rated current In= A <input type="checkbox"/> GYDW1-6300[III frame] <input type="checkbox"/> GYDW1-4000/3[II frame capacity expanding type] <input type="checkbox"/> GYDW1-4000/4[II frame 3+4] | | | | |
| Intelligent controller | Model "F" means generator protection Basic functions | | Additional functions or accessories can be added | |
| | L-type | <input type="checkbox"/> L2 | Long delay, instantaneous (3~10) In | 1. Light beam indication of load 2. MCU operation monitoring 3. Fault state indication 4. Fault memory 5. Instantaneous actuation test function <input type="checkbox"/> MCR switch in and off, and analog releasing <input type="checkbox"/> Pre-alarm, self-diagnosis, signal unit for OCR release alarm |
| | | <input type="checkbox"/> L3 | Long delay, short delay (3~10)In Instantaneous (10~20) In | |
| | | <input type="checkbox"/> L4 | Long delay, short delay (3~10)In Instantaneous (10~20) In, single phase grounding fault protection | |
| | M-type | <input type="checkbox"/> M | Long delay, short delay, instantaneous, single phase grounding fault protection | 1. Various states indications and value display 2. Ammeter 3. Fault memory 4. Thermal memory 5. Test <input type="checkbox"/> Load monitoring <input type="checkbox"/> Method 1 <input type="checkbox"/> Method 2 <input type="checkbox"/> Voltmeter <input type="checkbox"/> MCR switch in and off, and analog releasing <input type="checkbox"/> Pre-alarm, self-diagnosis, signal unit for OCR release alarm |
| | | <input type="checkbox"/> M/F | Long delay, short delay, instantaneous, pre-alarm | |
| | H-type | <input type="checkbox"/> H | 1. Long delay, short delay, instantaneous and load monitoring 2. Single phase grounding fault protection 3. Various states indications and value display 4. Ammeter 5. Voltmeter 6. Fault memory 7. Thermal memory | <input type="checkbox"/> MCR switch in and off, and analog releasing <input type="checkbox"/> RS485/232 converter <input type="checkbox"/> DP module |
| | | <input type="checkbox"/> H/F | 8. Test 9. RS485 serial interface 10. Alarm fault state | |
| | Power supply of intelligent controllers | | <input type="checkbox"/> AC220V <input type="checkbox"/> AC380V <input type="checkbox"/> DC110V <input type="checkbox"/> DC220V | |
| | | | <input type="checkbox"/> AC220V <input type="checkbox"/> AC230V <input type="checkbox"/> AC380V <input type="checkbox"/> AC400V | |
| | | <input type="checkbox"/> Under-voltage instantaneous release <input type="checkbox"/> Under-voltage delay release <input type="checkbox"/> 0.5s <input type="checkbox"/> 1s <input type="checkbox"/> 3s <input type="checkbox"/> 5s <input type="checkbox"/> 10s | | |
| 附件 | <input type="checkbox"/> Shunt release | <input type="checkbox"/> AC220V <input type="checkbox"/> AC380V <input type="checkbox"/> DC110V <input type="checkbox"/> DC220V | | |
| | <input type="checkbox"/> Switching in electromagnet | <input type="checkbox"/> AC220V <input type="checkbox"/> AC380V <input type="checkbox"/> DC110V <input type="checkbox"/> DC220V | | |
| | <input type="checkbox"/> Motor operating mechanism | <input type="checkbox"/> AC220V <input type="checkbox"/> AC380V <input type="checkbox"/> DC110V <input type="checkbox"/> DC220V | | |
| | <input type="checkbox"/> Mechanism interlocking | <input type="checkbox"/> Horizontal interlocking (soft interlock) <input type="checkbox"/> Vertical interlocking (lever interlock) <input type="checkbox"/> door interlock (key lock) | | |
| | <input type="checkbox"/> Key lock at switching out position | <input type="checkbox"/> lock <input type="checkbox"/> key (please fill in the number) | | |
| | <input type="checkbox"/> Door frame | | | |
| | <input type="checkbox"/> External single-phase grounding transformer | <input type="checkbox"/> Difference value type (3P+N) T <input type="checkbox"/> Underground current type (3P+N)W | | |
| | <input type="checkbox"/> External power supply module | Input <input type="checkbox"/> ~220V <input type="checkbox"/> ~380V <input type="checkbox"/> -110V <input type="checkbox"/> -220V PUT <input type="checkbox"/> -24V <input type="checkbox"/> -24V | | |
| Main circuit connection | <input type="checkbox"/> Horizontal connection (conventional supply) <input type="checkbox"/> vertical connection | | | |

Note:

1. If users selected additional functions or accessories for the controller, additional cost will be needed;
2. The long delay setting value of L-type controller is 10% decrement of In;
3. When users select H-type controllers, please indicate applied communication protocols (1. Proprietary communication protocol; 2. DP protocol; 3. Modbus)